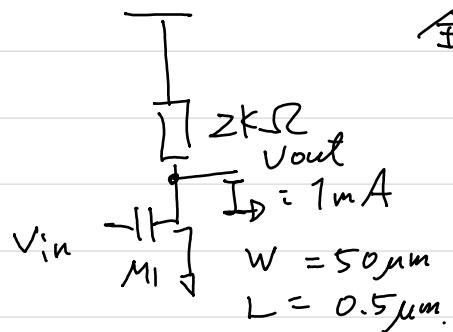


入力換算雑音電圧の導出を目標とする。

問題(7.1)

左図で帯域幅を100MHzとした時  
全入力換算熱雑音電圧は。



$$\overline{V_{out}^2} = 4kT \left( \frac{2}{3} g_m + \frac{1}{R_D} \right) R_D^2$$

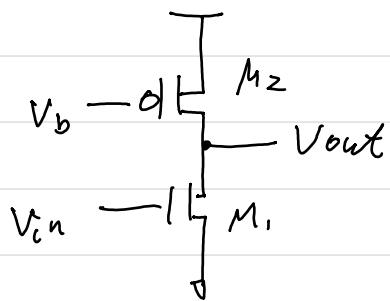
$$|A_V| = g_m R_D \text{ が } 2^{\text{次}} \text{ です}$$

1Hzあたりの  $\overline{V_{in}^2}$  は

$$\overline{V_{in}^2} = 4kT \left( \frac{2}{3} g_m + \frac{1}{g_m^2 R_D} \right)$$

問題(7.2)

入力換算電圧は。



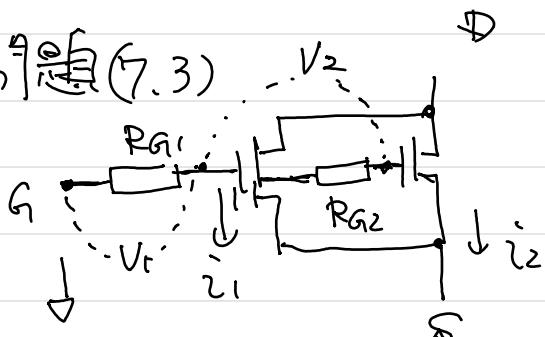
$$\overline{V_{in}^2} = 4kT \frac{2}{3} \frac{1}{g_m} \left( 1 + \frac{g_m^2}{g_m} \right)$$

$$(= 1)$$

$$\therefore R_D \approx \frac{1}{g_m^2} \text{ が } 2^{\text{次}}$$

問題(7.1)の式に代入  
すれば良い&OK。

問題(7.3)



$$\therefore g_m = g_{m2} = \frac{g_m}{n} \text{ とす。}$$

$$\overline{V_1^2} = \overline{V_2^2} = \dots = \overline{V_n^2} = 4kT \frac{R_G}{n} \text{ とす。} \quad (n > 2)$$

$$R_G = R_{G1} + R_{G2} + \dots$$

$$i_{total} = i_1 + i_2 + \dots + i_n$$

$$= g_m V_1 + g_{m2} (V_1 + V_2) + \dots$$

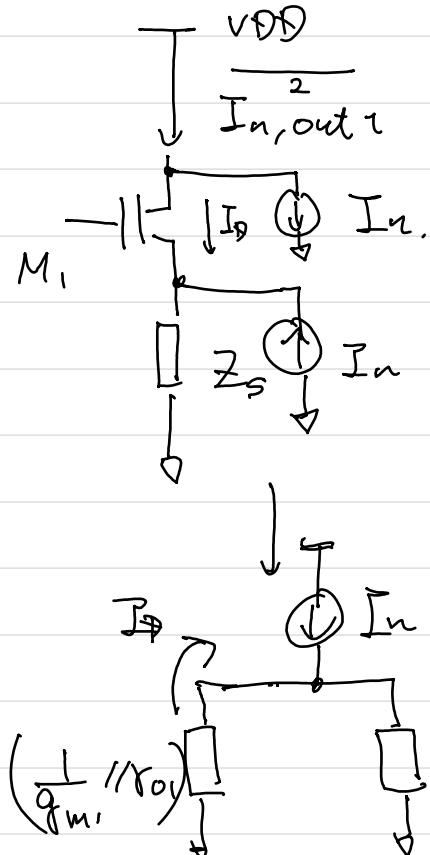
$$= \frac{g_m}{n} \{ nV_1 + (n-1)V_2 + \dots + V_n \}$$

$$i_{total} = 4kT \frac{R_G}{n} \left( \frac{g_m}{n} \right)^2 \{ n^2 + (n-1)^2 + \dots + 1 \} \Rightarrow 4kT \left( \frac{R_G}{3} \right) g_m^2$$

(3)

P.272 の補助定理。

問題(7.4) 左図の出力雑音電流を求める。



$$I_{n,out1} = I_D + I_n \text{ (KCL @ drain)}$$

$$I_D = -\frac{Z_s}{(\frac{1}{g_m} // r_{o1}) + Z_s} I_n$$

(Current divider  
符号が“+”で2つつづけに注意する)  
@ source

上式⑤'

$$I_{n,out1} = I_n \left( 1 - \frac{Z_s}{(\frac{1}{g_m} // r_{o1}) + Z_s} \right)$$

$$1 - \frac{Z_s}{Z_s + \frac{1}{(\frac{1}{g_m} + r_{o1})}}$$

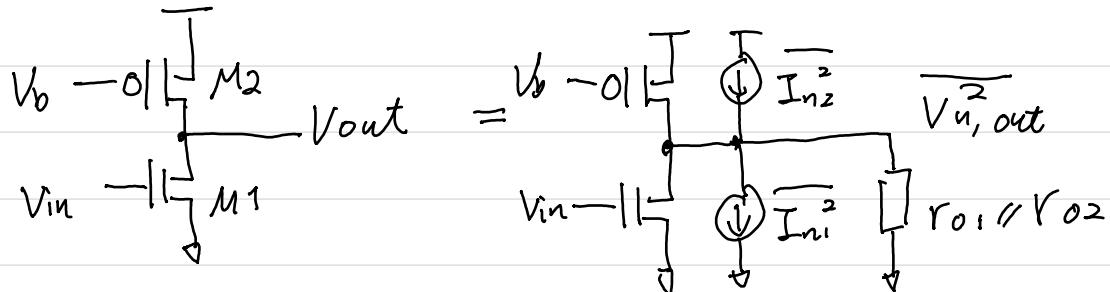
A < 1.

$$\left( \frac{Z_s}{Z_s + \frac{1}{A}} \right) \times A = \frac{A Z_s}{A Z_s + 1}$$

$$1 - \frac{A Z_s}{A Z_s + 1} = \frac{A Z_s + 1 - A Z_s}{A Z_s + 1} = \frac{1}{A Z_s + 1}$$

∴ (7.54) の  $I_{n,out1} = \frac{I_n}{Z_s (\frac{1}{g_m} + r_{o1}) + 1}$  も“道出式”。

問題(7.5) 式[7.59]を求めるための回路は.

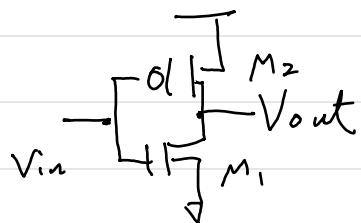


$$\overline{V_{n,out}} = 4kT \left( \frac{2}{3} g_{m1} + \frac{2}{3} g_{m2} \right) (r_{o1} \parallel r_{o2})^2$$

$$A_V = g_{m1} \cdot (r_{o1} \parallel r_{o2}) \text{ で 実}, 2$$

$$\overline{V_{n,in}} = 4kT \left( \frac{2}{3} \underbrace{\frac{g_{m1}}{g_{m1}^2}}_{\substack{\text{M2は電流源なので } g_{m2} \\ \text{最小にすれば } T \text{ が } \downarrow}} + \frac{2}{3} \frac{g_{m2}}{g_{m1}^2} \right) \dots [7.59]$$

次に以下の回路の入力換算雑音電圧をためる。



回路の利得は  $|A_V| = (g_{m1} + g_{m2})(r_{o1} \parallel r_{o2})$   
と計算される

$$\overline{V_{n,out}} = 4kT \frac{2}{3} (g_{m1} + g_{m2}) (r_{o1} \parallel r_{o2})^2$$

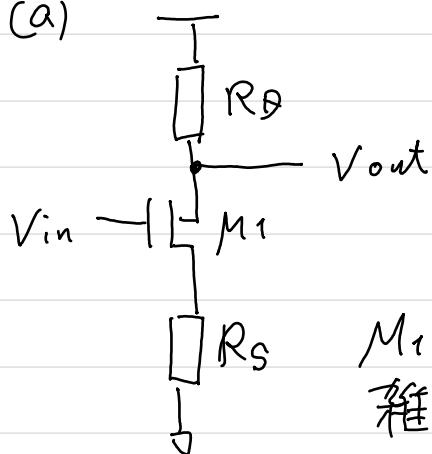
は先程と同じ。

$$\therefore \overline{V_{n,in}} = \frac{\overline{V_{n,out}}}{|A_V|^2} = 4kT \frac{2}{3} \left( \frac{1}{g_{m1} + g_{m2}} \right) \text{ となる。}$$

従って  $g_{m2}$  の増加に対して inverter で雑音が減少。  
Y-ス接地で雑音が増加する。

## 問題(7.6)

(a)



$$\text{回路の利得 (J) } |A_V| = \frac{g_{m1} R_D}{1 + g_{m1} R_S}$$

(3.57) 参照

$M_1$  の雑音は、補助定理により  
雑音電流をゲート電圧に換算し、

$$-i_L \left( \frac{V_{n,in}}{R_S} \right) = \frac{V_{n,in}}{R_S} \left( \frac{V_{n,in}^2}{4kT \frac{2}{3} g_{m1}} \right)$$

かつ回路の利得を乘すことで

$$\overline{V_{n,out,M1}^2} = 4kT \frac{2}{3} \frac{1}{g_{m1}} A_V^2 \times f_3.$$

$R_D$  の雑音は

$$\overline{V_{n,out,R}^2} = 4kT R_D.$$

$4kTR_S$  の  $A_V$  倍に考慮する。

$R_S$  の寄与 (J)  $\overline{V_{n,out,R_S}^2} =$

$$4kT \frac{1}{R_S} \left( \frac{R_S}{\frac{1}{g_{m1}} + R_S} \right)^2 R_D^2$$

$$\therefore \overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_V|^2} = 4kT \frac{2}{3} \frac{1}{g_{m1}} + 4kTR_S$$

$$+ 4kTR_D \left( \frac{1 + g_{m1} R_S}{g_{m1} R_D} \right)^2$$

(b).

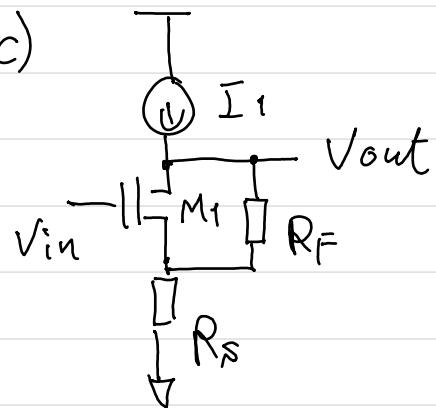


$$|A_V| = g_m \cdot \left( \frac{1}{g_{m1}} \parallel R_s \right)$$

$$V_{out} = (4kT \frac{2}{3} g_m + 4kT \frac{1}{R_s}) \left( \frac{1}{g_m} \parallel R_s \right)^2$$

$$\therefore \overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_V|^2} = 4kT \frac{2}{3} \frac{1}{g_m} + 4kT \frac{1}{g_m^2 R_s}$$

(c)

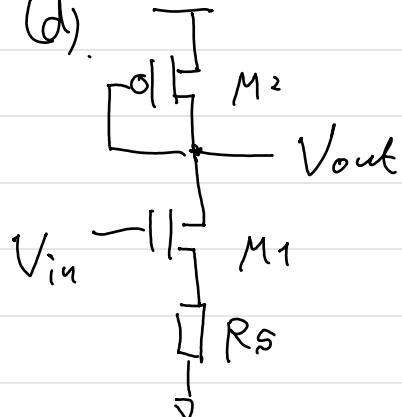


$$|A_V| = \frac{g_m}{1 + (g_m + \frac{1}{R_F}) R_s} \cdot R_{out}$$

(これは (a) の |A\_V| の分母に同じ)

$$R_{out} = R_s + (1 + g_m R_s) R_F.$$

(d).



$$|A_V| = \frac{g_{m1}}{1 + g_{m1} \cdot R_s} \cdot R_{out}$$

(3.51)  
参考

$$R_{out} = \frac{1}{g_{m2}}$$

$$\overline{V_{n,out}^2} = 4kT \frac{2}{3} g_{m2} R_{out}^2 + 4kT \frac{2}{3} \frac{1}{g_{m1}} |A_V|^2$$

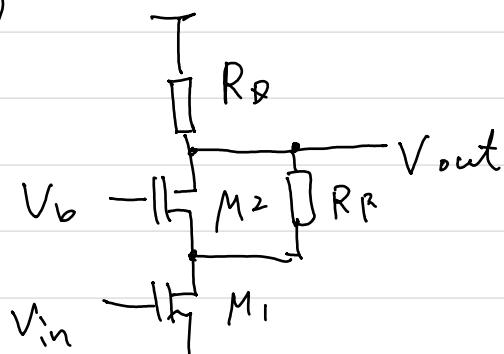
$$+ 4kT \frac{1}{R_s} \left( \frac{R_s}{\frac{1}{g_{m1}} + R_s} \right)^2 R_{out}^2$$

$$M1 の 寄与 \overline{V_{n1}^2} = \frac{I_{n1}^2}{g_{m1}^2} = 4kT \left( \frac{2}{3} g_{m1} \right) / g_{m1}^2 = 4kT |A_V|^2 / 4kT g_{m1}^2$$

これは |A\_V| が 1/3

で 2/3 です。

e)



$$|A_{v1}| = g_{m1} R_D$$

$$\overline{V_{u, \text{out}}^2} = \left( 4kT \frac{2}{3} g_{m1} + 4kT \frac{1}{R_D} \right) R_D^2$$

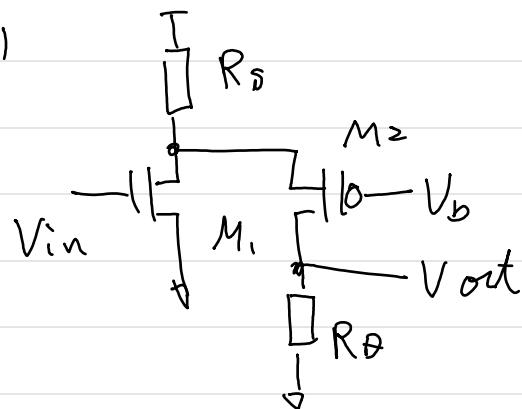
M<sub>2</sub> & R<sub>F</sub> は noise に 寄与 (左). ただし注意

$$r_{o1} = \infty$$

$$\overline{V_{u, \text{in}}^2} = \frac{\overline{V_{u, \text{out}}^2}}{|A_{v1}|^2} = 4kT \left( \frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_D} \right)$$

$$r_{o1} = \frac{1}{g_{m1}} \sim \frac{1}{\lambda I_D}$$

f)



$$|A_{v1}| = g_{m1} \left( \frac{g_{m2} R_F}{1 + g_{m2} R_S} \right) R_D$$

$$\text{note : } \frac{R_S}{g_{m2} + R_S} = \frac{g_{m2} R_S}{1 + g_{m2} R_S}$$

$$\begin{aligned} \overline{V_{u, \text{out}}^2} &= \underbrace{4kT \frac{1}{R_D} + 4kT \frac{2}{3} \frac{1}{g_{m2}} \left( \frac{g_{m2}}{1 + g_{m2} R_S} \right)^2}_{\text{R}_D \text{ 寄与}} + \\ &\quad \underbrace{4kT \frac{2}{3} \frac{1}{g_{m1}} \left( \frac{g_{m1} R_S}{g_{m2} + R_S} \right)^2 + 4kT \frac{1}{R_S} \left( \frac{R_S}{\frac{1}{g_{m2} + R_S}} \right)^2}_{M_1 \text{ の 寄与}} \end{aligned}$$

$$\frac{2}{3} \frac{|A_{v1}|^2}{g_{m1}}$$

$$\overline{V_{n,i_m}^2} = \overline{\frac{V_{n,out}^2}{|A_v|^2}} = 4kT \left[ \frac{2}{3} \frac{1}{g_{m_1}} + \frac{2}{3} \frac{1}{g_{m_2}} \cdot \frac{1}{(g_{m_2} R_s)^2} + \frac{1}{g_{m_1}^2 R_s} + \frac{1}{g_{m_1}^2 R_D} \left( \frac{1+g_{m_2} R_s}{g_{m_2} R_s} \right)^2 \right]$$

-X: [ ] ~~q~~ ナスコード ~~q~~ 寄り毛 M1 の 寄り毛 と 同様に:

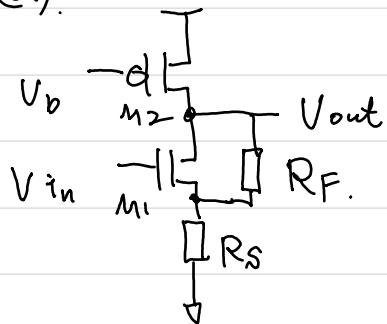
$$\left( \underbrace{\frac{g_{m_2}}{1+g_{m_2} R_s}}_{|A_v|} \right) \cdot R_s \text{ が } \frac{2}{3} \frac{1}{g_{m_2}} |A_v|^2$$

用い2

$$4kT \frac{2}{3} \frac{1}{g_{m_2}} \left( \frac{g_{m_2}}{1+g_{m_2} R_s} \right)^2$$

問題(7.7) 入力換算熱雑音電圧を求める。( $\lambda = \gamma = 0$  を仮定)

(a)



左図は問題(7.6)の(c)と同じ

$T\bar{\sigma}$  の $\bar{\sigma}^2$

$$|A_V| = \frac{g_{m1} R_{out}}{1 + (g_{m1} + \frac{1}{R_F}) R_S}$$

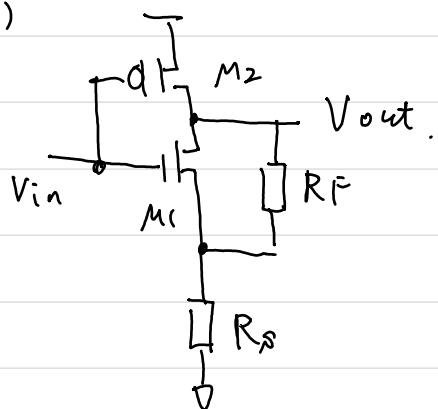
$$R_{out} = R_S + (1 + g_{m1} R_S) R_F$$

$$\begin{aligned} \overline{V_{n,out}^2} &= \left[ \underbrace{\frac{4kT}{3} \frac{g_{m1}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2}}_{M_1 \text{ 対応}} + \underbrace{\frac{4kT \frac{1}{R_F}}{(1 + (g_{m1} + \frac{1}{R_F}) R_S)^2}}_{R_F \text{ 対応}} \right. \\ &\quad \left. + \underbrace{\frac{4kT \frac{1}{R_S} R_S^2}{(R_S + \frac{1}{g_{m1} + 1/R_F})^2}}_{R_S \text{ 対応}} + \underbrace{\frac{4kT \frac{2}{3} g_{m2}}{g_{m1}}} \cdot R_{out}^2 \right] \cdot R_{out}^2 \end{aligned}$$

$$\therefore \overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_V|^2}$$

$$\begin{aligned} &= 4kT \left[ \frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1}^2 R_F} + R_S \left( 1 + \frac{1}{g_{m1} R_F} \right)^2 + \right. \\ &\quad \left. \frac{2}{3} g_{m2} \left( \frac{1 + (g_{m1} + \frac{1}{R_F}) R_S}{g_{m1}} \right)^2 \right] \end{aligned}$$

(b)



$$|A_V| = \left( g_{m_2} + \frac{g_{m_1}}{1 + (g_{m_1} + \frac{1}{R_F}) R_S} \right) \cdot R_{out}$$

~~M2 が 1 つ~~  
~~1 つ~~  
~~M1 が 2 つ~~  
~~2 つ~~

(a) の式と同じ

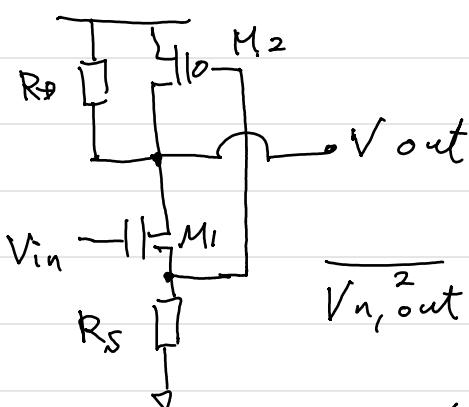
$$R_{out} = R_S + (1 + g_{m_1} R_S) R_F$$

$$\overline{V_{n,out}^2} = \left[ \frac{4kT \frac{2}{3} g_{m_1}}{(1 + (g_{m_1} + \frac{1}{R_F}) R_S)^2} + \frac{4kT \frac{1}{R_F}}{(1 + (g_{m_1} + \frac{1}{R_F}) R_S)^2} \right. \\ \left. + \frac{4kT \frac{1}{R_S} \cdot R_S^2}{(R_S + \frac{1}{g_{m_1}} // R_F)^2} + 4kT \frac{2}{3} g_{m_2} \right] \cdot R_{out}^2$$

↑ = a 式は前へ戻ると全く同じ



(c)



$$|A_V| = \left( \frac{g_{m_1}}{1 + g_{m_1} R_S} \right) (1 + g_{m_2} R_D) R_D$$

(d) = c の導出

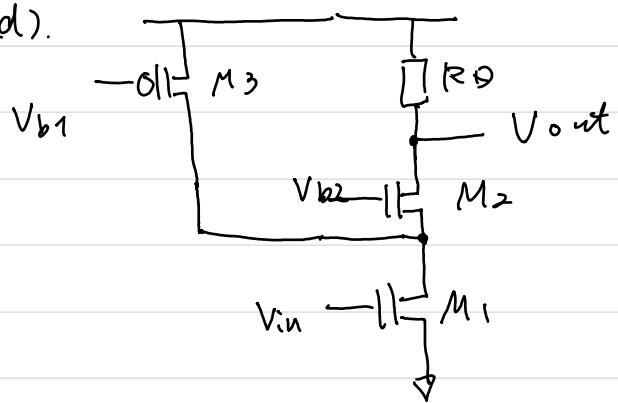
$$\overline{V_{n,out}^2} = 4kTR_D + 4kT \frac{2}{3} g_{m_2} R_D +$$

$$4kT \frac{2}{3} \frac{1}{g_{m_1}} |A_V|^2 +$$

(e) = d の導出

$$4kT \frac{1}{R_S} \left[ \frac{R_S}{\frac{1}{g_{m_1}} + R_S} - \frac{\frac{1}{g_{m_1}} R_S}{\frac{1}{g_{m_1}} + R_S} \cdot g_{m_2} \right] R_D^2$$

(d).



$$|A_v| = g_{m_1} R_D.$$

$$\overline{V_{n,out}^2} = \left[ 4RT \frac{1}{R_D} + 4RT \frac{2}{3} g_{m_3} + 4RT \frac{2}{3} g_{m_1} \right] R_D^2$$

M2, M3の入力には寄与しない。  $\therefore r_{o1} > r_{o3} = \infty$

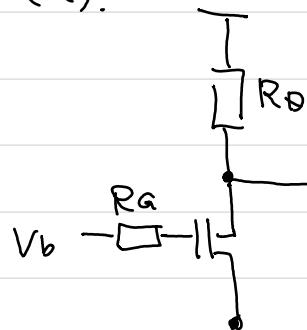
$$\overline{V_{n,in}^2} = \frac{\overline{|V_{n,out}|^2}}{|A_v|^2} = 4RT \left[ \frac{2}{3} \frac{1}{g_{m_1}} + \frac{2}{3} \frac{g_{m_3}}{g_{m_1}^2} + \frac{1}{g_{m_1}^2 R_D} \right]$$

$$r_{o1} = \frac{1}{g_{m_1}}$$

トスコード時は1次に寄与しない！ ④ 37.4.4の議論を参考。

P<sup>14</sup>題(7.8) 入力換算電圧の導出

(a).



$$|A_V| = g_m R_D$$

$$\overline{V_{n,out}^2} = \left[ 4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_m + 4kT R_G g_m \right] R_D^2$$

Vin. (入力を短絡して出力端で観測されるノイズ)

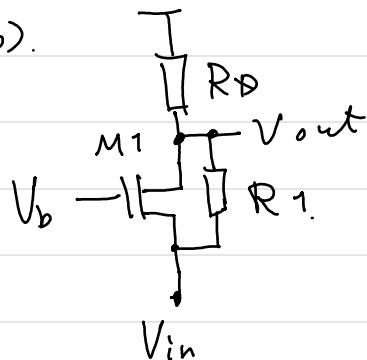
一、入力を開放して出力端で観測される

$$\text{熱雑音電流は } \overline{I_{n,out}^2} = \frac{4kT}{R_D}$$

二、電流が入力にそのまま換算されて  $\overline{I_{n,in}^2} = \frac{4kT}{R_D}$

C.F. 3.

(b).

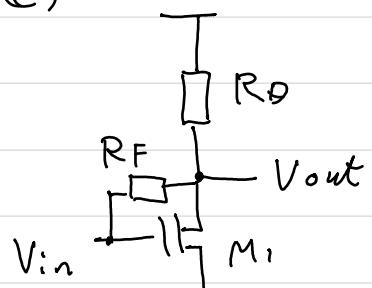


$$|A_V| = \left( g_m + \frac{1}{R_1} \right) (R_1 \parallel R_D)$$

$$\overline{V_{n,out}^2} = \left[ 4kT \frac{1}{R_D} + 4kT \frac{1}{R_1} + 4kT \frac{2}{3} g_m \right] \times (R_1 \parallel R_D)^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_V|^2} = 4kT \left( \frac{1}{g_m + \frac{1}{R_1}} \right)^2 \left[ \frac{2}{3} g_m + \frac{1}{R_1} + \frac{1}{R_D} \right]$$

(C)

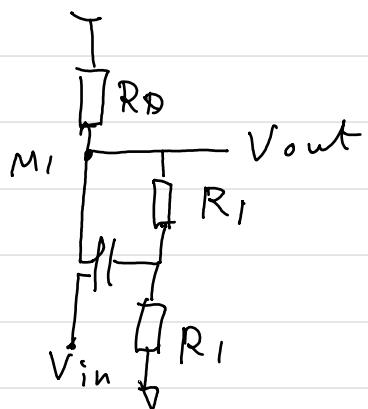


$$A_V = \left( -g_{m1} + \frac{1}{R_F} \right) (R_F \parallel R_D)$$

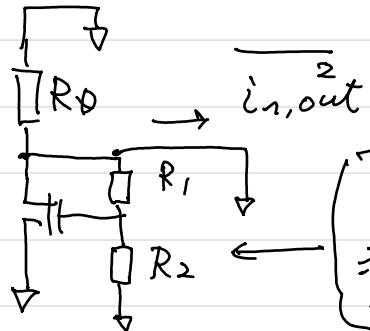
$$\overline{V_{n,out}^2} = 4kT \left( \frac{1}{R_F} + \frac{1}{R_D} + \frac{2}{3} g_{m1} \right) \times (R_F \parallel R_D)^2$$

$$\overline{V_{n,in}^2} = \frac{\overline{V_{n,out}^2}}{|A_V|^2} = 4kT \left( -g_{m1} + \frac{1}{R_F} \right)^2 \left[ \frac{2}{3} g_{m1} + \frac{1}{R_F} + \frac{1}{R_D} \right]$$

(d)



入力を短絡して得られる雑音電流



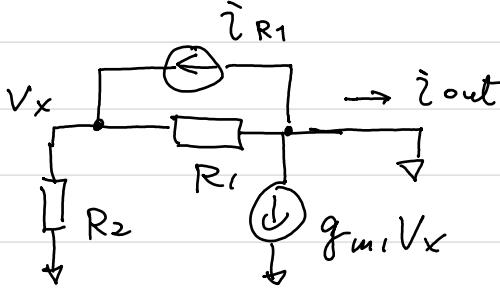
$M_1 \approx R_1, R_2 \ll R_D$   
 つまり雑音は  $R_1, R_2$  が  
 増幅され  $M_1$  で減衰する

$$\overline{i_{n,out}^2} = 4kT \frac{1}{R_D} + 4kT \frac{2}{3} g_{m1} + \overline{i_{noise,R1}^2} + \overline{i_{noise,R2}^2}$$

$$\overline{i_{noise,R1}^2} = 4kT \frac{1}{R_1} |A_{I,R1}|^2$$

$$\overline{i_{noise,R2}^2} = 4kT \frac{1}{R_2} |A_{I,R2}|^2$$

次に  $A_{I,R_1}$  を求めよ。

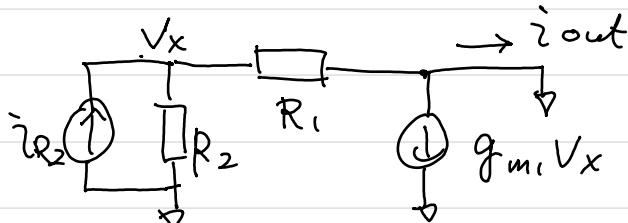


$$A_{I,R_1} = \frac{i_{out}}{i_{R_1}}$$

$$= - \left[ 1 + (R_1/R_2) \left( g_{m1} - \frac{1}{R_1} \right) \right]$$

$$\left( \begin{array}{l} i_{out} = (i_{R_1} + g_{m1}V_x) \\ \cancel{i_{R_1} = \frac{V_x}{R_2}} \end{array} \right) \rightarrow \cancel{i_{R_1} = \frac{V_x}{R_2}}$$

次に  $A_{I,R_2}$  を求めよ



$$A_{I,R_2} = \frac{i_{out}}{i_{R_2}}$$

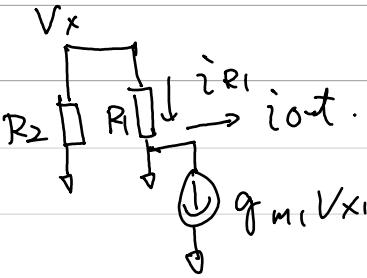
$$= \left[ \frac{R_2}{R_1 + R_2} - g_{m1} (R_1/R_2) \right]$$

$$\therefore \overline{i_{n,out}^2} = 4kT \frac{1}{R_D} + 4kT \frac{2}{3} \cdot g_{m1} +$$

$$4kT \frac{1}{R_1} \left( 1 + (R_1/R_2) \left( g_{m1} - \frac{1}{R_1} \right) \right)^2 +$$

$$4kT \frac{1}{R_2} \left[ \frac{R_2}{R_1 + R_2} - g_{m1} (R_1/R_2) \right]^2$$

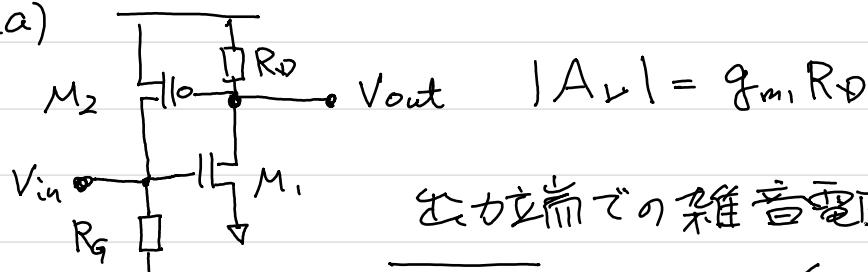
$$\overline{V_{n,i_n^2}} = \frac{\overline{i_{n,out}^2}}{g_{m1}^2}$$



## 問題 7.9 入力換算電圧

の計算 ( $\lambda = \gamma = 0$  とする)

(a)



出力端での雑音電圧は

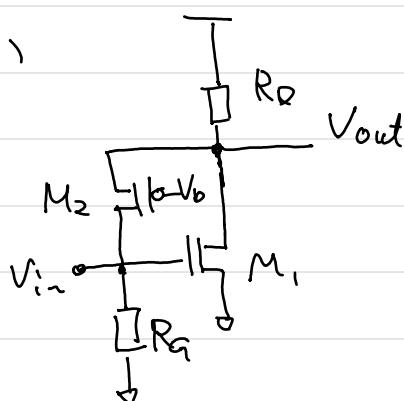
$$\overline{V_{n, out}^2} = 4kT \left( R_D + \frac{2}{3} g_{m_1} R_D^2 \right)$$

従って入力換算電圧は  $\overline{V_{n, in}^2} = 4kT \left( \frac{1}{g_{m_1}^2 R_D} + \frac{2}{3} \frac{R_D^2}{g_{m_1}} \right)$ 一方入力換算電流は回路の入力インピーダンス  $R_G$  に対して同じ出力雑音電圧を生じるので

$$\overline{I_{n, in}^2} = 4kT \left( \frac{R_D}{R_G^2} + \frac{2}{3} g_{m_1} \frac{R_D^2}{R_G^2} \right) \text{である}$$

$$(R_G^2 \cdot \overline{I_{n, in}^2} = \overline{V_{n, out}^2})$$

(b)



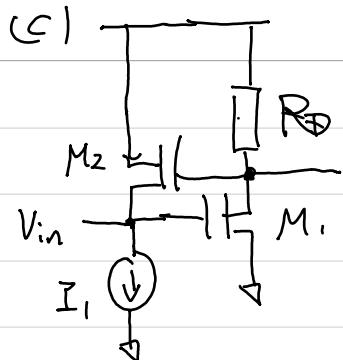
出力端での雑音電圧は

$$|A_V| = g_{m_1} \left( R_D \parallel \frac{1}{g_{m_2}} \right)$$

$$\overline{V_{n, out}^2} = 4kT \left( \frac{1}{R_D} + \underbrace{\frac{2}{3} g_{m_1} + \frac{2}{3} g_{m_2}}_{\text{誤り}} \right) \left( R_D \parallel \frac{1}{g_{m_2}} \right)$$

$$\overline{V_{n, in}^2} = \frac{\overline{V_{n, out}^2}}{|A_V|^2} \text{ である。}$$

トランジスタの換算電流



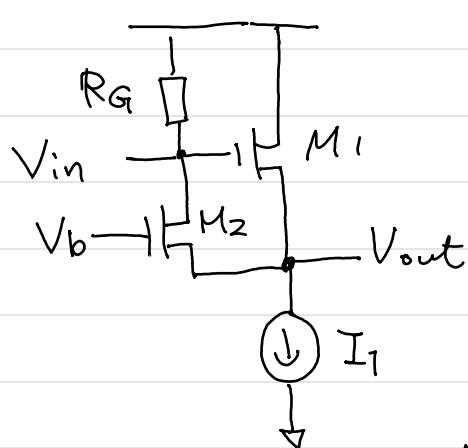
$M_2$  は  $V_{out}$  の "ト" に接続されるが、なぜか  $V_{out}$  の  $\overline{V_{n, out}^2}$  に影響する。図 (a) と同様。

$$|A_v| = g_m \cdot R_D$$

$$\overline{V_{n, out}^2} = 4kT \left( \frac{2}{3} g_{m1} + \frac{1}{R_D} \right) R_D^2$$

$$\overline{V_{n, in}^2} = \frac{\overline{V_{n, out}^2}}{|A_v|^2} = 4kT \left( \frac{2}{3} \frac{1}{g_{m1}} + \frac{1}{g_{m1} \cdot R_D} \right)$$

(d) (誤植)

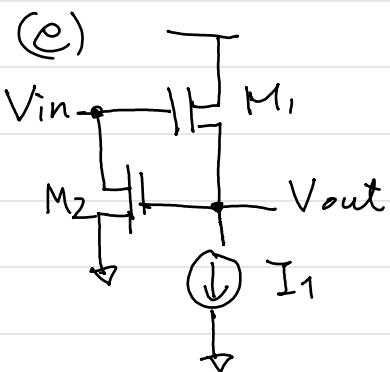


$$|A_v| = \frac{g_{m1}}{g_{m1} + g_{m2}} \quad \left( R_{out} = \frac{1}{g_{m1} + g_{m2}} \right)$$

$$\overline{V_{n, out}^2} = 4kT \left( \frac{2}{3} g_{m1} + \frac{2}{3} g_{m2} \right) \times \left( \frac{1}{g_{m1} + g_{m2}} \right)^2$$

おまけ

$$R_{out} = \left( \frac{1}{g_{m1}} \parallel \frac{1}{g_{m2}} \right) = \frac{1}{g_{m1} + g_{m2}}$$



これは  $R_{out}$  が  $1$  のとき  $|A_v| = 1$

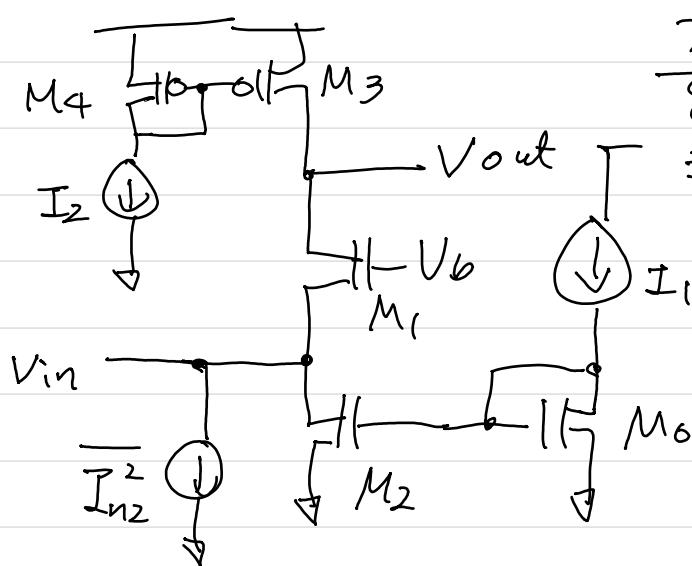
$$\overline{V_{n, in}^2} = \overline{V_{n, out}^2} = 4kT \frac{2}{3} g_{m1}$$

$M_2$  は何の意味があるのか?

"ト" が  $V_{out}$  につながる。つまり出力が  $V_{out}$  に接続される。

誤植

# 問題 7.10. 入力換算 $\sqrt{f}$ 雜音電圧の計算



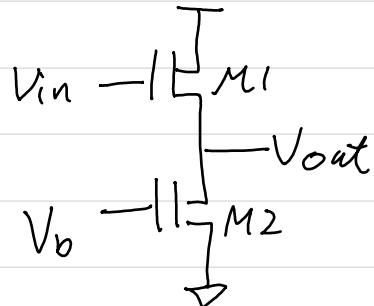
入力端とグランドに直結されて  
入力端における  $\sqrt{f}$  雜音を  
求める。  
(寄生は  $M_1, M_3, M_4$ )

$$\overline{V_{n,out}^2} = \frac{1}{Coxf} \left( \frac{k_n g_{m_1}^2}{W_1 L_1} + \frac{k_p g_{m_3}^2}{W_3 L_3} + \frac{k_p g_{m_3}^2}{W_4 L_4} \right) (r_o \parallel r_o)^2$$

$$|A_v| = (g_{m_1} + g_{mb_1}) (r_o \parallel r_o)^2$$

$$\overline{V_{n,in}^2} = \frac{1}{Coxf} \left[ \frac{g_{m_1}^2 k_n}{(W_1 L_1)} + \frac{g_{m_3}^2 k_p}{(W_3 L_3)} + \frac{g_{m_3}^2 k_p}{(W_4 L_4)} \right] \frac{1}{(g_{m_1} + g_{mb_1})^2}$$

問題 7.11 Y-2つアロウの入力換算 1/2 総音電圧の計算



$$|A_D| = g_m R_{out},$$

p.88 参照

$$R_{out} = \left( \frac{1}{g_{m1}} \parallel \frac{1}{g_{mb1}} \parallel \frac{1}{g_{m2}} \parallel \frac{1}{g_{mb2}} \right)$$

4+添え字長変更

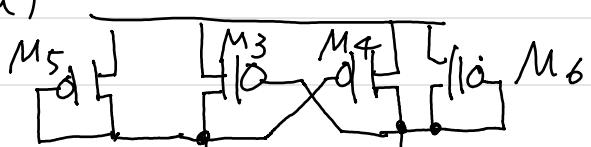
出力端において 1/2 総音電圧は

$$\overline{V_{n,out}^2} = \frac{k_n}{C_{oxf}} \left( \frac{g_{m1}^2}{W_1 L_1} + \frac{g_{m2}^2}{W_2 L_2} \right) R_{out}^2$$

$$\therefore \overline{V_{n,in}^2} = \frac{k_n}{C_{oxf}} \left( \frac{1}{W_1 L_1} + \frac{g_{m2}^2}{W_2 L_2 g_{m1}^2} \right)$$

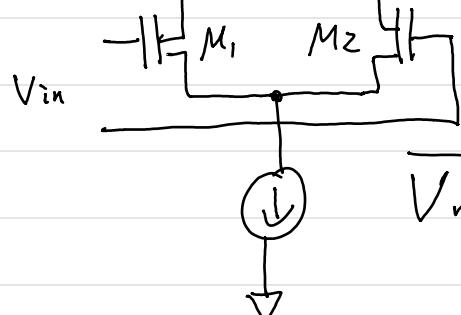
問題 7.12 入力換算 热総音電圧の計算

(a)



$$g_{m3,4} = 0.5 g_{m5,6} \text{ とする}$$

回路の利得は  $|A_D| = g_m R_{out}$



出力端で観測される総音電圧は

$$\overline{V_{n,out}^2} = 4kT \frac{2}{3} (g_{m1} + g_{m2} + g_{m3} + \dots + g_{m6})$$

$$X R_{out}^2$$

$$\therefore \overline{V_{n,in}^2} = 4kT \frac{2}{3} \left( \frac{2}{g_{m1}} + \frac{3g_{m5}}{g_{m1}} \right)$$