

SAD-MAD converter survey and needs

Demin Zhou

Acknowledgements:

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FCC-ee design meeting, CERN, Mar. 03, 2017

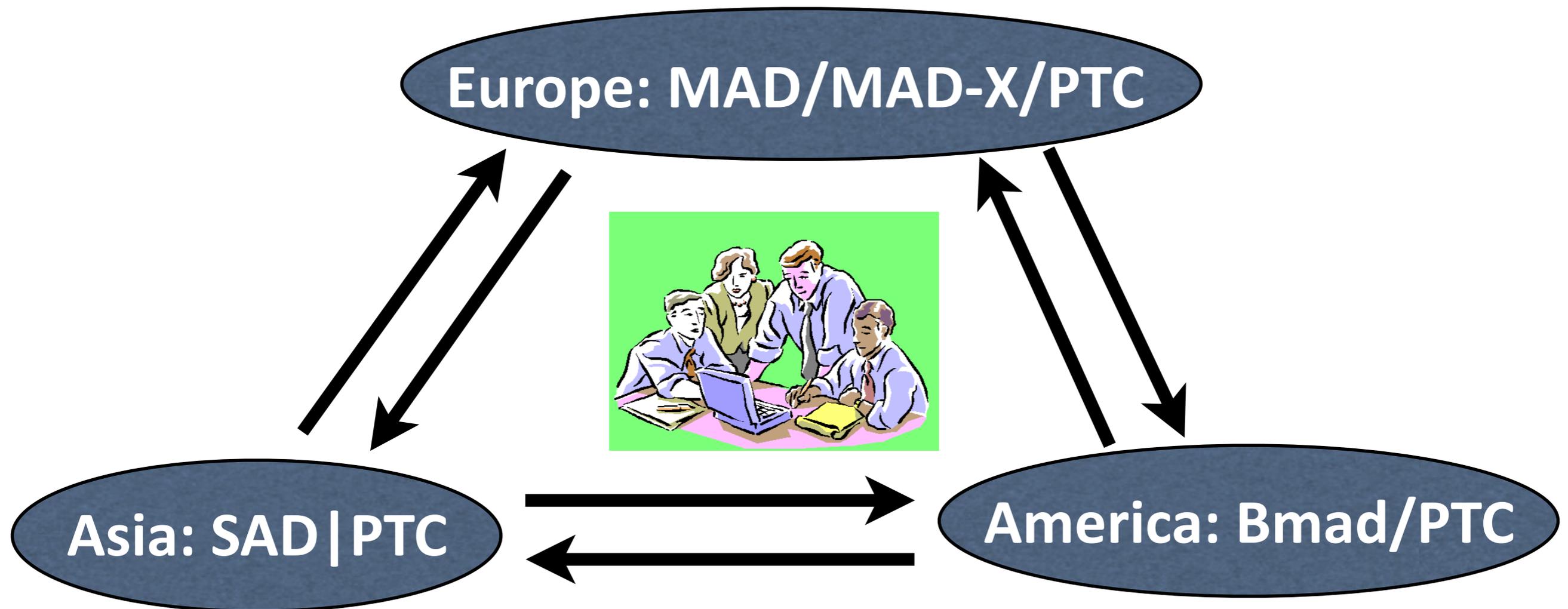
Outline

- **Introduction**
- **Current status**
 - Existing translators
 - Examples for lattice translation
 - An example of benchmark
- **Symplectic tracking in SAD**
 - Transfer maps for DRIFT, SOL, etc.
 - Hard-edge and soft-edge fringe maps
- **Summary**

1. Introduction

➤ Motivation: To improve communications

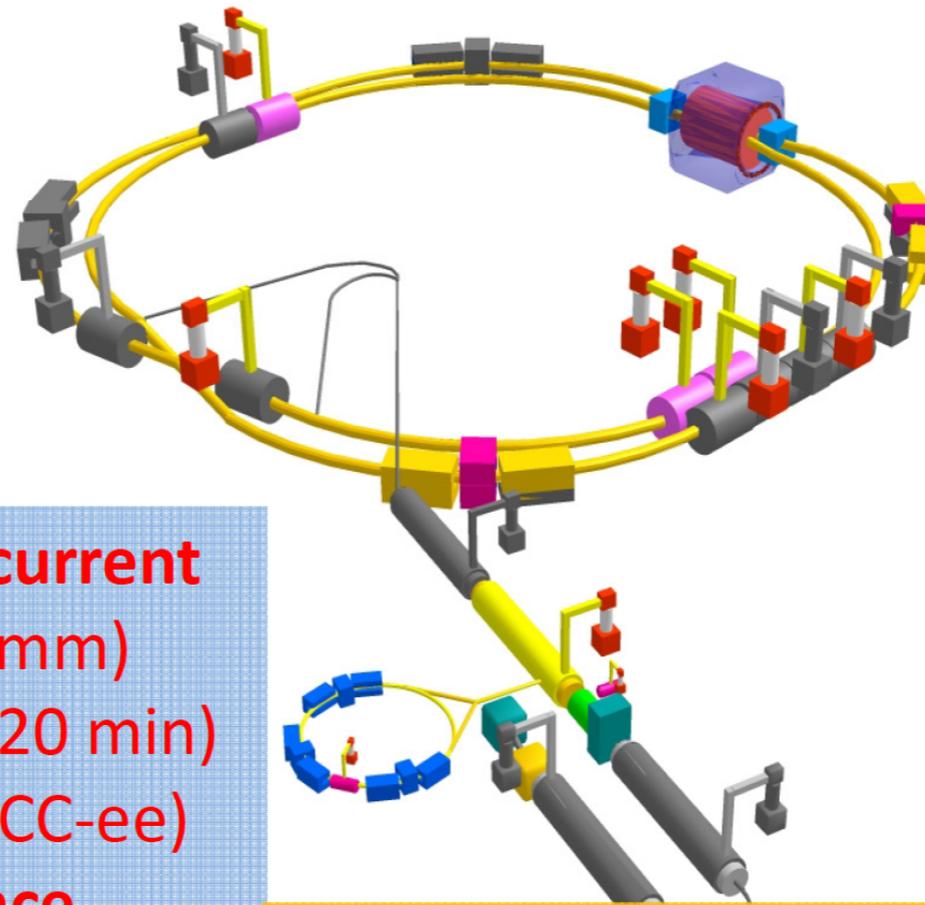
- **SAD:** TRISTAN, KEKB, J-PARC, SuperKEKB, ...
- **Bmad:** CESR, ERL, ...
- **MAD/MAD-X:** PS, LEP, LHC, FCCs, ...



1. Introduction

➤ Motivation: To improve collaborations on projects like SuperKEKB and FCCs

SuperKEKB = FCC-ee demonstrator



top up injection at high current
 $\beta_y^* = 300 \mu\text{m}$ (FCC-ee: 1 mm)
lifetime 5 min (FCC-ee: ≥ 20 min)
 $\epsilon_y/\epsilon_x = 0.25\%$ (similar to FCC-ee)
off momentum acceptance
($\pm 1.5\%$, similar to FCC-ee)
 e^+ production rate ($2.5 \times 10^{12}/\text{s}$,
FCC-ee: $< 1.5 \times 10^{12}/\text{s}$ (Z cr.waist))

SuperKEKB goes beyond FCC-ee, testing all concepts

1. Introduction

➤ References for this topic

- **D. Zhou et al., “Lattice translation between accelerator simulation codes for SuperKEKB”, in Proceedings of IPAC'16, Busan, Korea, May. 08-13, 2016.**
- **D. Zhou, “SuperKEKB lattice translation”, MAD-X meeting, CERN, Sep. 22, 2016, <https://indico.cern.ch/event/565330/>.**
- **D. Zhou, “Recent progress on lattice translation from SAD to MAD-X for FCC-ee”, 47th FCC-ee design meeting, Feb. 24, 2017.**
- **D. Sagan, “The Bmad Reference Manual”, <https://www.classe.cornell.edu/~dcs/bmad/manual.html>.**
- **SAD Home Page, <http://acc-physics.kek.jp/SAD/> (SAD manual under preparation).**
- **MAD-X user’s guide, <http://mad.web.cern.ch/mad/>**

2. Current status

➤ Efforts for lattice translations: SAD \leftrightarrow MAD/MAD-X

- MAD \rightarrow SAD: H. Koiso(KEK), Y. Wang(IHEP), et al.
- MAD-X \rightarrow SAD: A. Morita(KEK, 2008)
- SAD \rightarrow MAD: Y. Wang(IHEP), et al.
- SAD \rightarrow MAD-X: A. Morita(KEK), K. Oide(KEK), Y. Wang(IHEP), et al.
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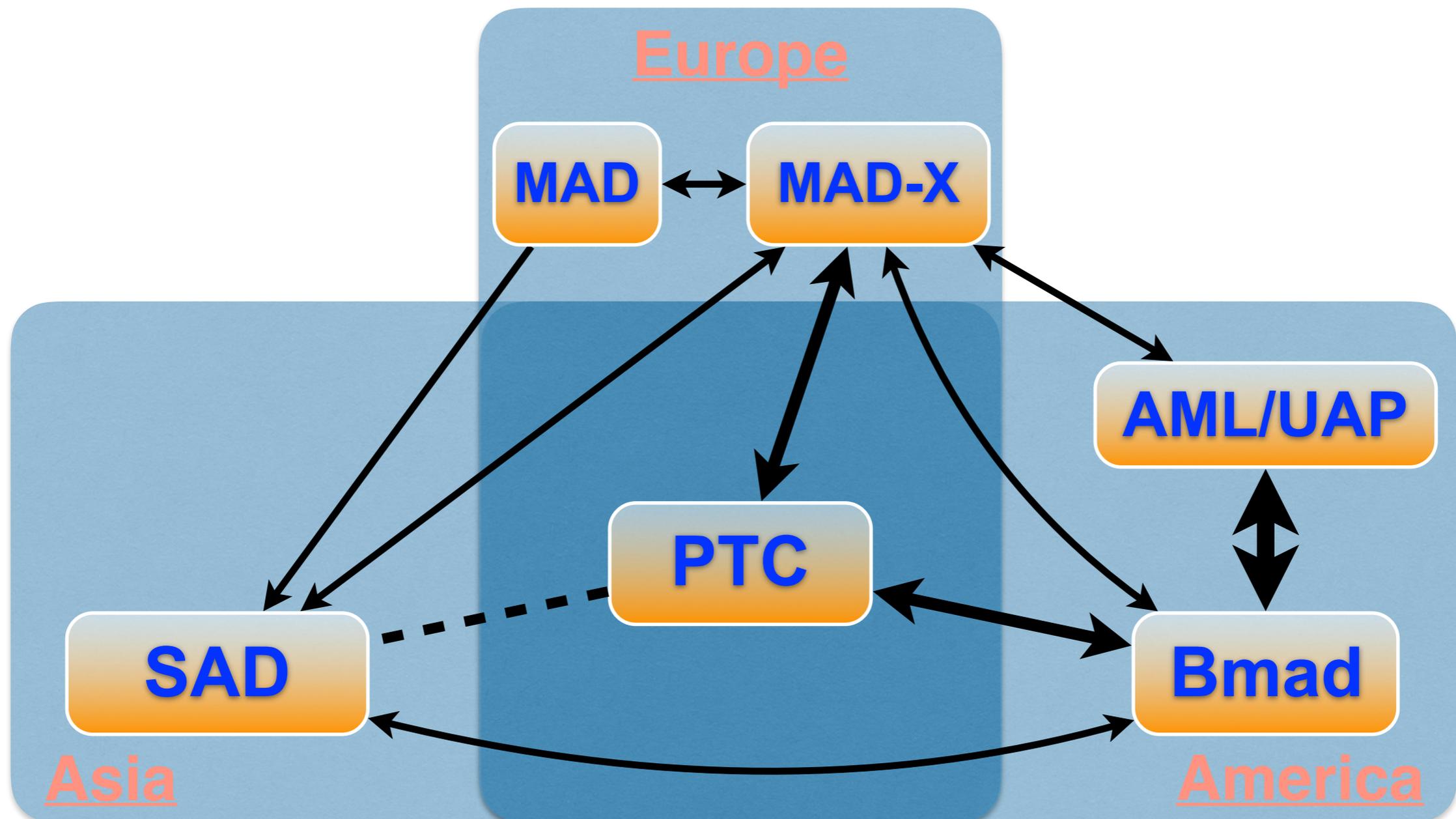
➤ Efforts for lattice translations: Other tools

- SAD \leftrightarrow Bmad: D. Sagan(Cornell), E. Forest(KEK), et al.
- Bmad \leftrightarrow UAP \leftrightarrow MAD-X: D. Sagan(Cornell), et al.
- Bmad \leftrightarrow MAD/MAD-X, Bmad \leftrightarrow PTC, MAD-X \leftrightarrow PTC: D. Sagan(Cornell), E. Forest(KEK), P. Skowronski, et al.
- SAD \rightarrow AT: N. Carmignani, S.M. Liuzzo(ESRF), et al.
-

2. Current status

➤ Efforts for lattice translations

- SAD and PTC: developed at KEK, many shared features (transfer maps, symplectic integrator, ...)
- PTC integrated into MAD-X and Bmad



2. Current status

➤ Archive for examples of lattice translation

- Uploaded to MAD-X svn repository: <http://svnweb.cern.ch/world/wsvn/madx/branches/madX-SAD/tools/translators/> (still under construction) [Thanks to L. Deniau and I. Tecker]
- Classified by routes of translations
- Used programs: MAD-X/PTC, SAD, Bmad/PTC, UAP
- Sample jobs prepared for demonstration and benchmarks

SUBVERSION REPOSITORIES  MADX

madx | calm | English - English

(root)/branches/madX-SAD/tools/translators/ - Rev 6099

Rev HEAD Go

Last modification | View Log | Download | RSS feed

LAST MODIFICATION

Rev 6078 2017-01-17 17:35:00

Author: dezhou

Log message:

Creating subdirectory ./tools/translators containing the SAD <-> MADX translators

Path	Last modification	Log	Download	RSS
branches/	6078 41d 23h dezhou	Log		RSS
madX-SAD/	6078 41d 23h dezhou	Log	Download	RSS
cmake/	5933 168d 03h ylevinse	Log	Download	RSS
doc/	6058 48d 00h alatina	Log	Download	RSS
examples/	6029 82d 04h rdemaria	Log	Download	RSS
lib32/	2785 2035d 02h ylevinse	Log	Download	RSS
lib64/	2594 2231d 23h frs	Log	Download	RSS
libs/	6061 46d 00h skowron	Log	Download	RSS
make/	5959 138d 08h ldeniau	Log	Download	RSS
scripts/	6010 100d 07h ldeniau	Log	Download	RSS
src/	6061 46d 00h skowron	Log	Download	RSS
syntax/	6015 95d 07h ylevinse	Log	Download	RSS
testing/	4206 1335d 02h ghislain	Log	Download	RSS
tests/	6068 42d 03h skowron	Log	Download	RSS
tools/	6078 41d 23h dezhou	Log	Download	RSS
numdiff/	6015 95d 07h ylevinse	Log	Download	RSS
translators/	6078 41d 23h dezhou	Log	Download	RSS

translators/	6105	3m	dezhou
bmad_to_sad/	6105	3m	dezhou
mad8_to_sad/	6105	3m	dezhou
madx_to_bmad_via_uap/	6105	3m	dezhou
madx_to_ptc/	6105	3m	dezhou
madx_to_sad/	6105	3m	dezhou
sad_to_bmad/	6105	3m	dezhou
sad_to_madx/	6105	3m	dezhou
README	6105	3m	dezhou

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2. Current status

➤ A benchmark of MAD-X and SAD: CLIC FFS

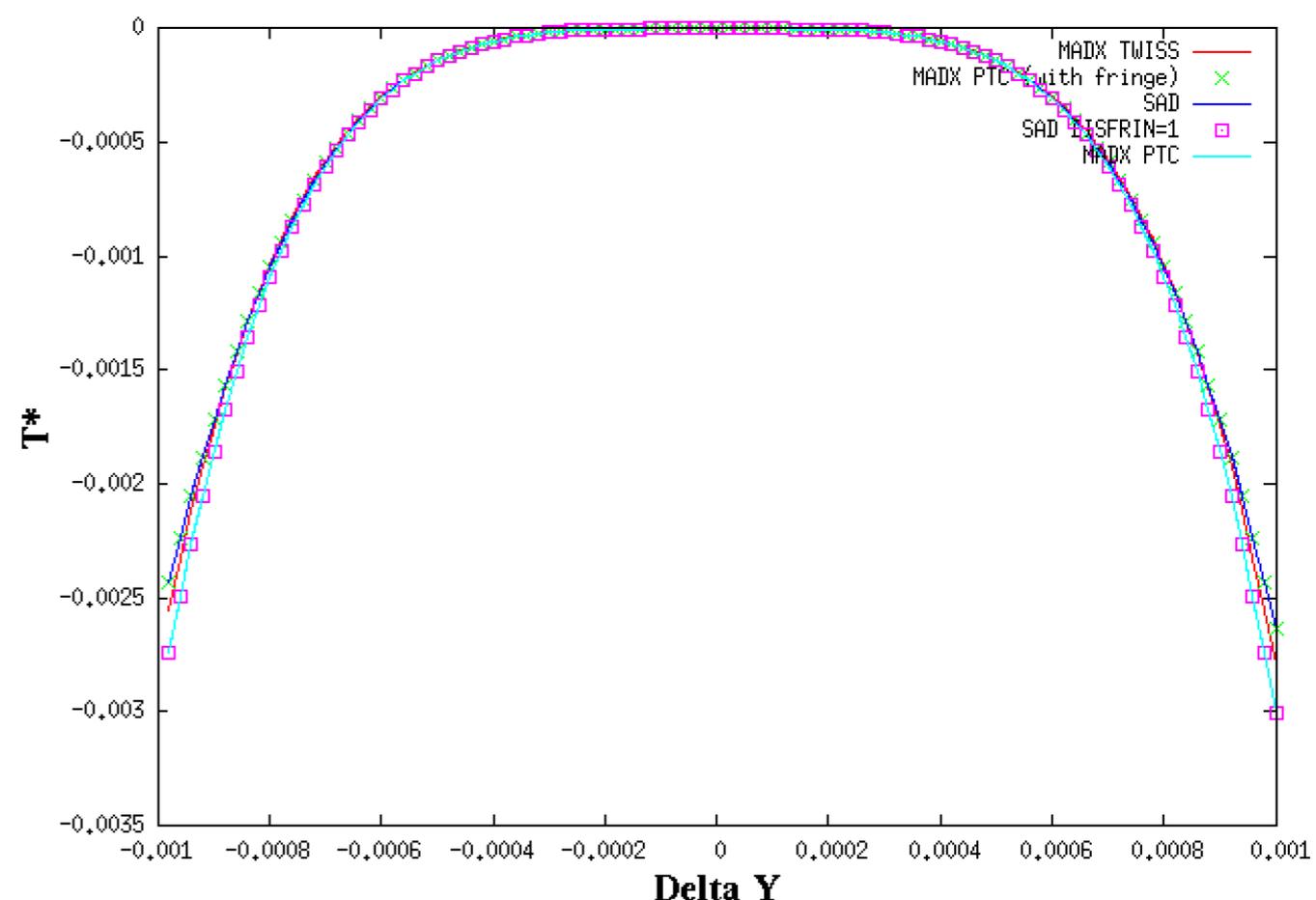
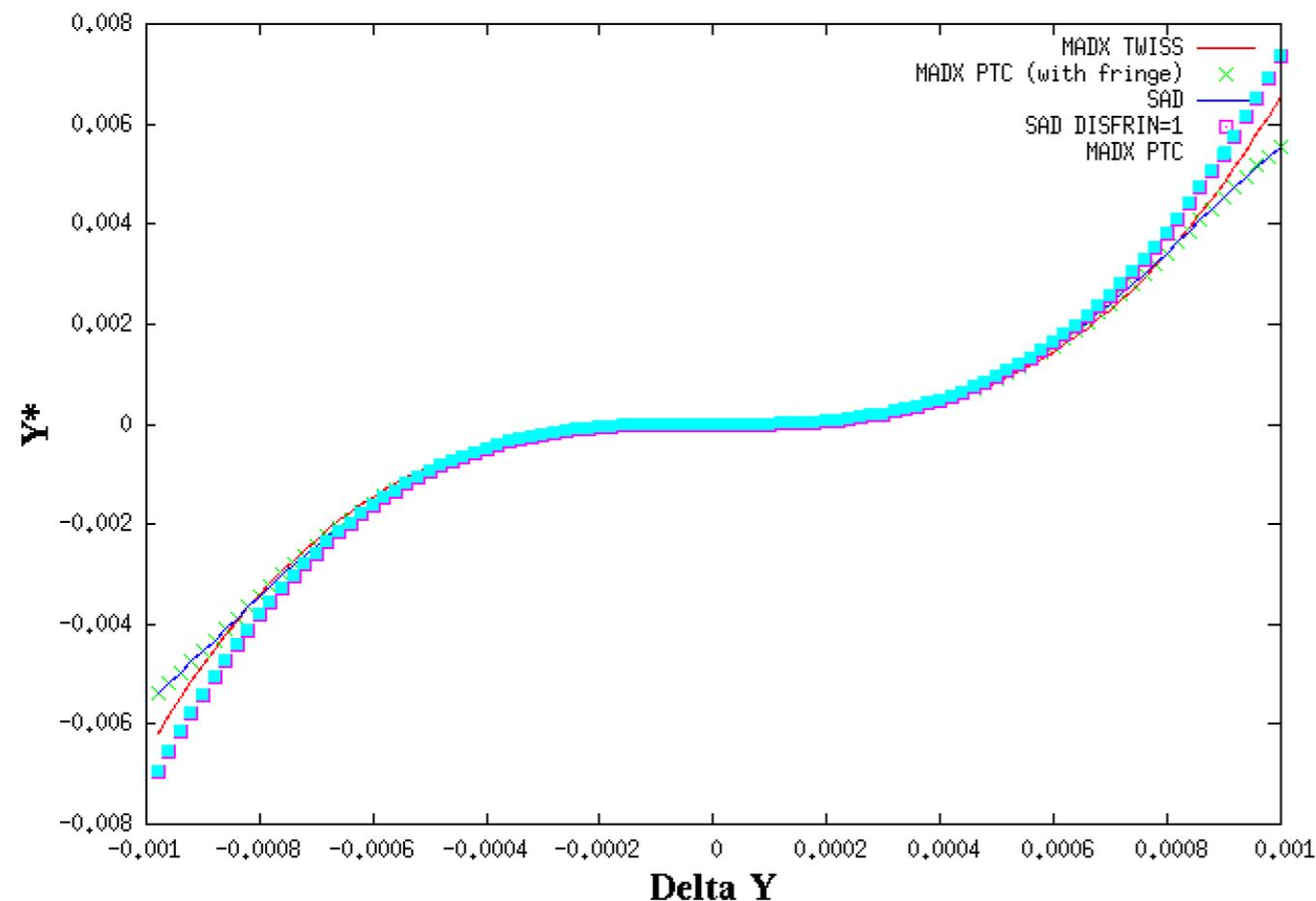
- **Conditions:**

- * Track “orbit” for a test particle

- * No soft edge fringe, no solenoid

- **Hard edge fringe: SAD=PTC≈MAD-X**

- **For longitudinal transformation: SAD=PTC≈MAD-X (Settings for PTC: ICASE=6, TIME=true)**



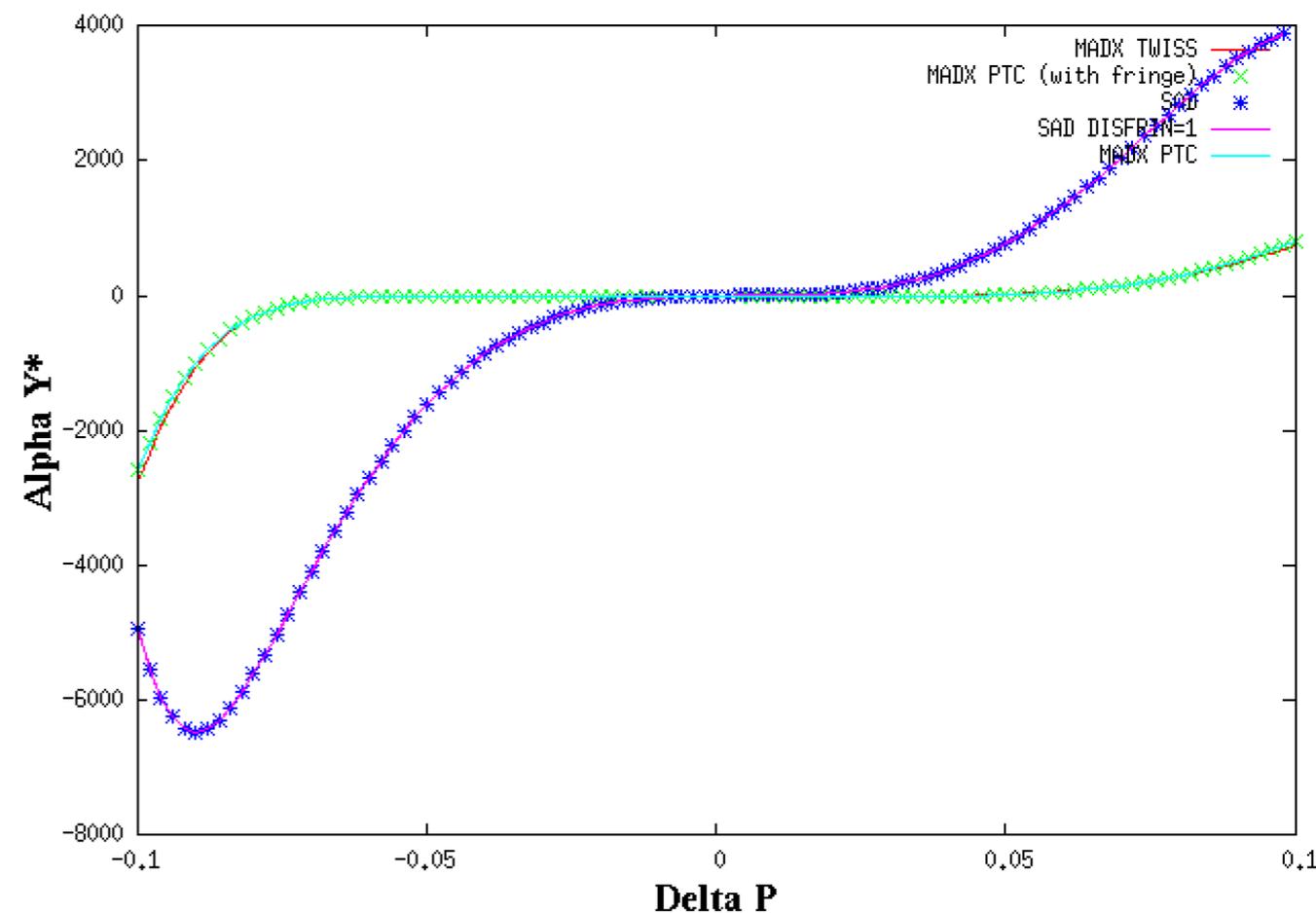
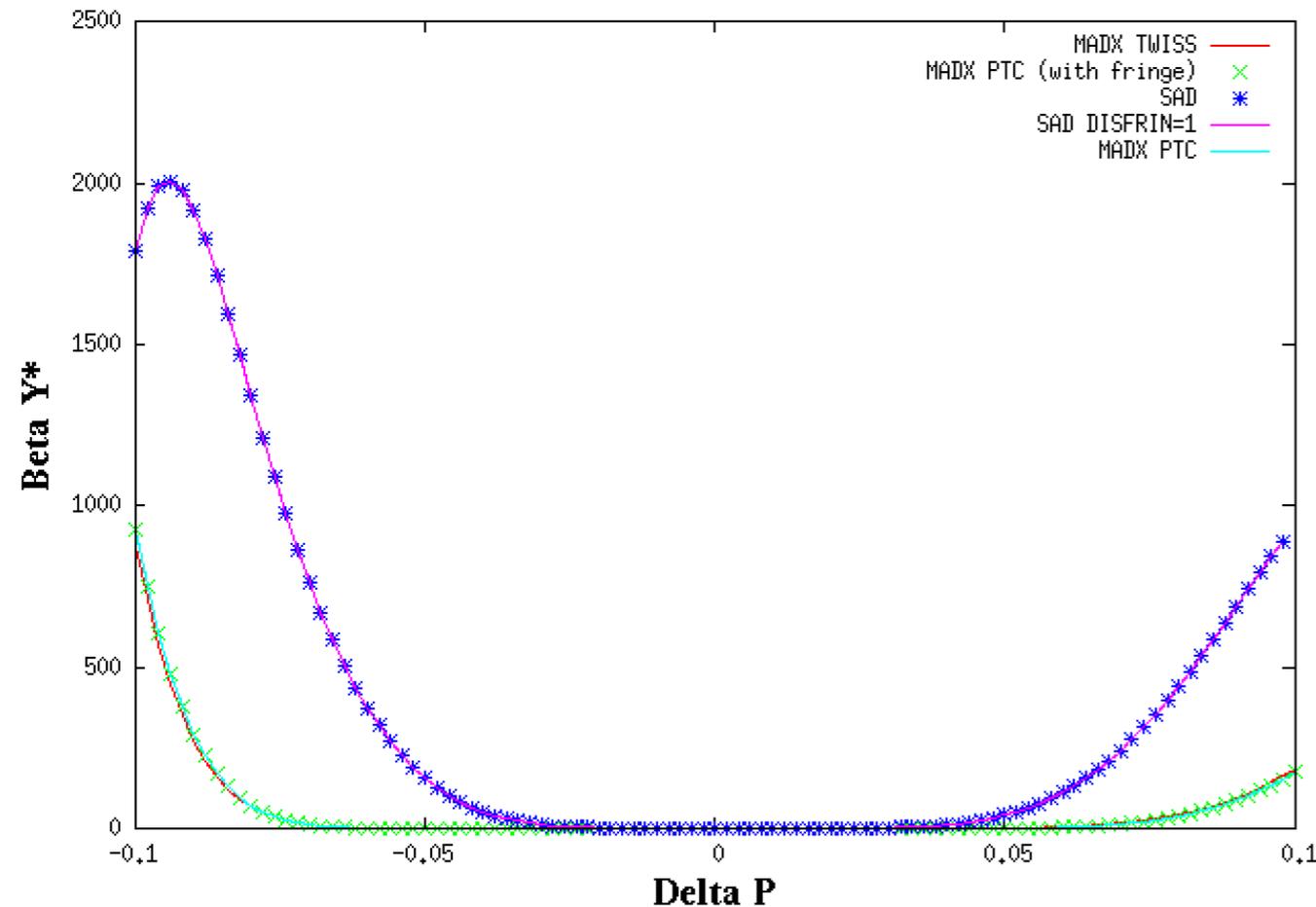
2. Current status

➤ A benchmark of MAD-X and SAD: CLIC FFS

- Conditions:
 - * Twiss with momentum offset
 - * No soft edge fringe, no solenoid
- Hard edge fringe: Negligible
- SAD: High-order chromaticity due to DRIFT
- MAD-X/PTC: ICASE=5 (Need proper settings?)

For a DRIFT:

$$\beta(\delta, s) = \beta_0 + \frac{s^2}{\beta_0(1+\delta)^2}$$



Courtesy of Paul Thrane

3. Symplectic tracking in SAD

► Hamiltonian

• Hamiltonian for a relativistic particle in an electromagnetic field in Cartesian coordinate system:

$$H = \sqrt{(\vec{p} - q\vec{A})^2 c^2 + m_0^2 c^4} + q\phi$$

• Hamiltonian used in SAD:

$$H(x, p_x, y, p_y, z, \delta) = \frac{E}{P_0 v_0} - \left(1 + \frac{x}{\rho_x} + \frac{y}{\rho_y}\right) \sqrt{(1 + \delta)^2 - (p_x - \hat{A}_x)^2 - (p_y - \hat{A}_y)^2} - \left(1 + \frac{x}{\rho_x} + \frac{y}{\rho_y}\right) \hat{A}_s$$

Reference synchronous particle: $P_0 = \gamma_0 m_0 v_0$

$$p = P/P_0 = 1 + \delta \quad p_x = P_x/P_0, \quad p_y = P_y/P_0$$

$$\hat{A}_x = \frac{qA_x}{P_0} = \frac{A_x}{B\rho}, \quad \hat{A}_y = \frac{qA_y}{P_0} = \frac{A_y}{B\rho}, \quad \hat{A}_s = \frac{qA_s}{P_0} = \frac{A_s}{B\rho}$$

Quadrupole: $\vec{A} \equiv (A_x, A_y, A_s) = (0, 0, \frac{1}{2}B_1(y^2 - x^2))$

$$B_1 = \partial B_y / \partial x$$

Solenoid: $\vec{B} = (0, 0, B_s)$

$$K_1 = \frac{B_1}{B_0 \rho} = \frac{eB_1}{P_0}$$

$$\vec{A} \equiv (A_x, A_y, A_s) = \left(-\frac{1}{2}B_s y, \frac{1}{2}B_s x, 0\right)$$

3. Symplectic tracking in SAD

➤ A DRIFT (L) is nonlinear ...

- Hamiltonian for a DRIFT:

$$H(x, p_x, y, p_y, z, \delta) = \frac{1}{v_0} \sqrt{p^2 c^2 + \left(\frac{m_0 c^2}{P_0}\right)^2} - \sqrt{p^2 - p_x^2 - p_y^2}$$

- Symplectic transformation (exact solution):

$$x_2 = x_1 + \frac{p_{x1}}{\sqrt{p^2 - p_{x1}^2 - p_{y1}^2}} L,$$

$$p_{x2} = p_{x1},$$

$$y_2 = y_1 + \frac{p_{y1}}{\sqrt{p^2 - p_{x1}^2 - p_{y1}^2}} L,$$

$$p_{y2} = p_{y1},$$

$$z_2 = z_1 - \left(\frac{p}{\sqrt{p^2 - p_{x1}^2 - p_{y1}^2}} - \frac{v}{v_0} \right) L = z_1 + \left(1 - \frac{p}{\sqrt{p^2 - p_{x1}^2 - p_{y1}^2}} \right) L - \frac{v_0 - v}{v_0} L$$

3. Symplectic tracking in SAD

➤ A DRIFT with solenoid field (L, BZ)

- Hamiltonian for a DRIFT + solenoid field:

$$H(x, p_x, y, p_y, z, \delta) = \frac{E}{P_0 v_0} - \sqrt{p^2 - (p_x + \frac{1}{2} b_z y)^2 - (p_y - \frac{1}{2} b_z x)^2} \quad b_z = \frac{eB_z}{P_0}$$

- Symplectic transformation (exact solution):

$$x_2 = x_1 + \frac{(1+\delta) \sin \phi}{b_z} p_{xi} + \frac{(1+\delta)(1-\cos \phi)}{b_z} p_{yi},$$

$$y_2 = y_1 - \frac{(1+\delta)(1-\cos \phi)}{b_z} p_{xi} + \frac{(1+\delta) \sin \phi}{b_z} p_{yi},$$

$$p_{x2} = p_{xi} \cos \phi + p_{yi} \sin \phi - \frac{b_z}{2(1+\delta)} y_2,$$

$$p_{y2} = -p_{xi} \sin \phi + p_{yi} \cos \phi + \frac{b_z}{2(1+\delta)} x_2,$$

$$z_2 = z_1 + \left[\frac{\sqrt{1-p_{xi}^2-p_{yi}^2}-1}{\sqrt{1-p_{xi}^2-p_{yi}^2}} - \Delta v \right] L$$

$$\phi = \frac{b_z L}{(1+\delta) \sqrt{1-p_{xi}^2-p_{yi}^2}},$$

$$p_{xi} = p_{x1} + \frac{b_z y_1}{2(1+\delta)},$$

$$p_{yi} = p_{y1} - \frac{b_z x_1}{2(1+\delta)},$$

$$\Delta v = \frac{v_0 - v}{v_0}$$

- The SOL element in SAD is special: NO attribute of L

- The next case: L≠0, BZ≠0, K0≠0, SK0≠0 [Solvable]

3. Symplectic tracking in SAD

➤ Fringe fields: Bend soft edge fringe (From Bmad manual)

Bmad defines the bend soft edge map in terms of the field integral F_{H1} for the entrance end and F_{H2} for the exit end given by (see Eq. (3.5))

$$F_{H1} \equiv F_{int} H_{gap} = \int_{pole} ds \frac{B_y(s) (B_{y0} - B_y(s))}{2 B_{y0}^2} \quad (19.46)$$

With a similar equation for F_{H2} . The soft edge map is then

$$\begin{aligned} x_2 &= x_1 + c_1 p_z \\ p_{y2} &= p_{y1} + c_2 y_1 - c_3 y_1^3 \\ z_2 &= z_1 + \frac{1}{1 + p_{z1}} \left(c_1 p_{x1} + \frac{1}{2} c_2 y_1^2 - \frac{1}{4} c_3 y_1^4 \right) \end{aligned} \quad (19.47)$$

For the entrance face:

$$c_1 = \frac{g_{tot} F_{H1}^2}{2(1 + p_z)}, \quad c_2 = \frac{2 g_{tot}^2 F_{H1}}{1 + p_z}, \quad c_3 = 0 \quad (19.48)$$

with g_{tot} is the total bending strength

$$g_{tot} = g + g_{err} \quad (19.49)$$

g being the reference bend strength and g_{err} being bend the difference between the actual and reference bend strengths (§3.5).

For the exit face, the substitution is made

$$\begin{aligned} F_{H1} &\rightarrow F_{H2} \\ g_{tot} &\rightarrow -g_{tot} \end{aligned} \quad (19.50)$$

When the SAD bend soft edge map is used (§4.20), the map is the same except that the value of c_3 is

$$c_3 = \frac{8 g_{tot}^2}{F_{H1} (1 + p_z)} \quad (19.51)$$

3. Symplectic tracking in SAD

➤ Fringe fields: Quad. soft edge fringe (From Bmad manual)

Only the quadrupole soft edge fringe is modeled in *Bmad*. The model is adapted from SAD[SAD]. The fringe map is:

$$\begin{aligned}x_2 &= x_1 e^{g_1} + g_2 p_{x1} \\p_{x2} &= p_{x1} e^{-g_1} \\y_2 &= y_1 e^{-g_1} - g_2 p_{y1} \\p_{y2} &= p_{y1} e^{g_1} \\z_2 &= z_1 - \left[g_1 x_1 p_{x1} + g_2 \left(1 + \frac{g_1}{2} \right) e^{-g_1} p_{x1}^2 \right] + \left[g_1 y_1 p_{y1} + g_2 \left(1 - \frac{g_1}{2} \right) e^{g_1} p_{y1}^2 \right]\end{aligned}\tag{19.53}$$

where

$$\begin{aligned}g_1 &= K_1 \text{fq1} \\g_2 &= K_1 \text{fq2}\end{aligned}\tag{19.54}$$

K_1 is the quadrupole strength, and fq1 and fq2 are the fringe quadrupole parameters. These parameters are related to the field integral I_n via

$$\begin{aligned}\text{fq1} &= I_1 - \frac{1}{2} I_0^2 \\ \text{fq2} &= I_2 - \frac{1}{3} I_0^3\end{aligned}\tag{19.55}$$

where I_n is defined by

$$I_n = \frac{1}{K_1} \int_{-\infty}^{\infty} (K_1(s) - H(s - s_0) K_1) (s - s_0)^n ds\tag{19.56}$$

and $H(s)$ is the step function

$$H(s) = \begin{cases} 1 & s > 0 \\ 0 & s < 0 \end{cases}\tag{19.57}$$

and it is assumed that the quadrupole edge is at s_0 and the interior is in the region $s > s_0$.

3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe (From Bmad manual)

The magnetic multipole hard edge fringe field is modeled using the method shown in Forest[Forest98]. For the m^{th} order multipole the Lee transform is (Forest Eq. (13.29)):

$$f_{\pm} = \mp \Re \left[\frac{(b_m + i a_m) (x + i y)^{m+1}}{4(m+2)(1+\delta)} \left\{ x p_x + y p_y + i \frac{m+3}{m+1} (x p_x - y p_y) \right\} \right] \\ \equiv \frac{p_x f^x + p_y f^y}{1+\delta} \quad (19.58)$$

The multipole strengths a_m and b_m are given by (14.9) and the second equation defines f^x and f^y . On the right hand side of the first equation, the minus sign is appropriate for particles entering the magnet and the plus sign is for particle leaving the magnet. Notice that here the multipole order m is equivalent to $n - 1$ in Forest's notation.

With this, the implicit multipole map is (Forest Eq. (13.31))

$$x^f = x - \frac{f^x}{1+\delta} \\ p_x = p_x^f - \frac{p_x^f \partial_x f^x + p_y^f \partial_x f^y}{1+\delta} \\ y^f = y - \frac{f^y}{1+\delta} \\ p_y = p_y^f - \frac{p_x^f \partial_y f^x + p_y^f \partial_y f^y}{1+\delta} \\ \delta^f = \delta \\ z^f = \frac{p_x^f f^x + p_y^f f^y}{(1+\delta)^2} \quad (19.59)$$

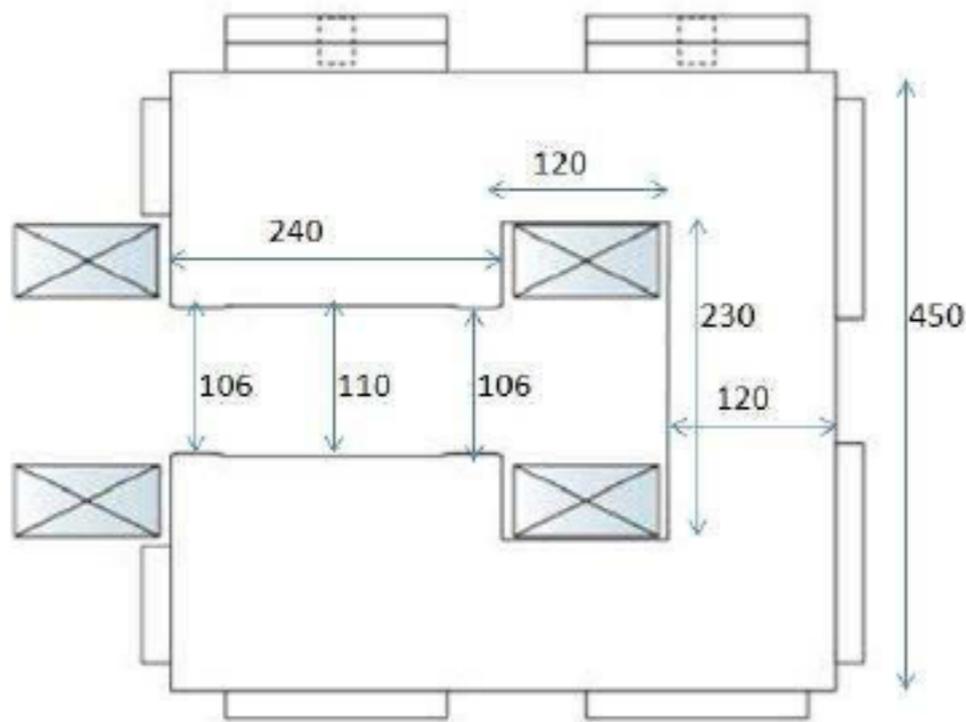
Note:

This equation is general,
applying for BEND, QUAD,
SEXT, ... to arbitrary order.
But BEND is special!

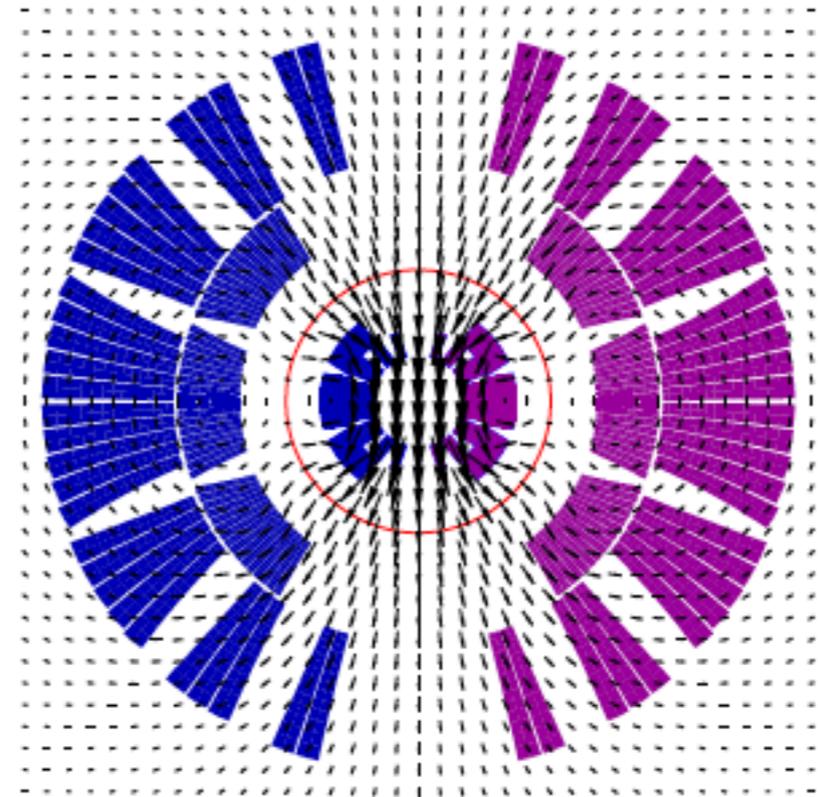
3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe for BEND

- Two models found for **hard-edge fringe**
 - * E. Forest: “Parallel-plate” shape (popular theory)
 - * Y. Cai: Round shape (SLAC-PUB-11181, apply for SC magnets?)



Usual case
(From SuperKEKB TDR)

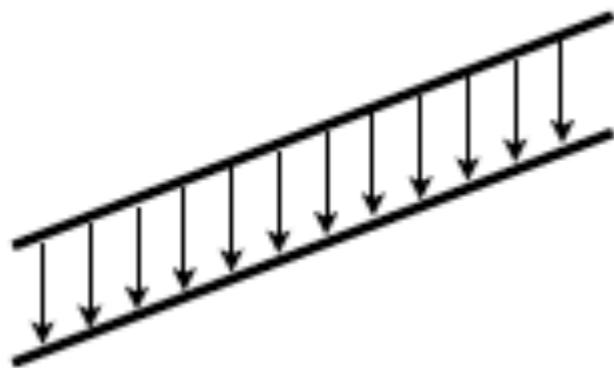


SC magnet
(From S. Russenschuck's textbook, 2010)

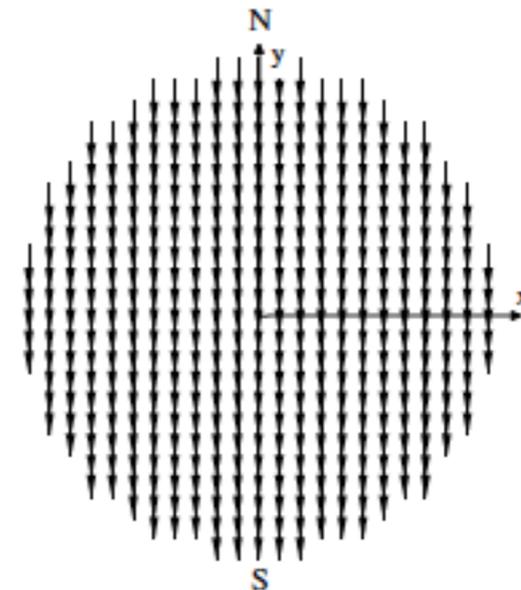
3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe for BEND

- Maxwellian solution for hard-edge dipole field
 - * G. Lee-Whiting et al. => E. Forest et al.
 - * S. Caspi et al. => M. Bassetti et al. => Y. Cai et al.



The model for wide magnet.
The field is confined at region of
 $-b < y < b$ and $-\infty < x < \infty$



The model for harmonics expansion.
The field is confined inside a circle
with $r < r_0$
(From S. Russenschuck's textbook,
2010)

3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe for BEND

- Maxwellian solution for hard-edge dipole field

- * G. Lee-Whiting et al. => E. Forest et al.

- * S. Caspi et al. => M. Bassetti et al. => Y. Cai et al.

$$A_s = -xB(s) = -xB_0\theta(s).$$

$$\vec{A} = (A_x, 0, A_s)$$

$$\nabla \times \nabla \times \vec{A} = 0$$

$$A_x = B_0 \sum_{n=1}^{\infty} \frac{(-1)^n \theta^{(2n-1)}(s)}{(2n)!} y^{2n}$$

$$A_y = 0$$

$$A_x = \frac{1}{2}(x^2 - y^2) \sum_{p=0}^{\infty} \frac{1}{2+p} G_{1,2p+1}(s)(x^2 + y^2)^p,$$

$$A_y = xy \sum_{p=0}^{\infty} \frac{1}{2+p} G_{1,2p+1}(s)(x^2 + y^2)^p,$$

$$A_s = -x \sum_{p=0}^{\infty} G_{1,2p}(s)(x^2 + y^2)^p.$$

$$G_{n,2p}(s) = (-1)^p \frac{n!}{4^p(n+p)!p!} \frac{d^{2p}G_{n,0}(s)}{ds^{2p}},$$

$$G_{n,2p+1}(s) = \frac{dG_{n,2p}(s)}{ds},$$

$$A_y \neq 0$$

3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe for BEND

- Maxwellian solution for hard-edge dipole field

- * G. Lee-Whiting et al. => E. Forest et al.

- * S. Caspi et al. => M. Bassetti et al. => Y. Cai et al.

Field distribution with hard-edge:

$$B_x = 0,$$

$$B_y(y, s) = B_0 \sum_{n=1}^{\infty} \frac{(-1)^n y^{2n} \theta^{(2n)}(s)}{(2n)!},$$

$$B_s(y, s) = -2B_0 \sum_{n=1}^{\infty} \frac{(-1)^n n y^{2n-1} \theta^{(2n-1)}(s)}{(2n)!}.$$

Field distribution with hard-edge:

$$B_x(x, y, s) = -\frac{1}{2} B_0 x y \sum_{p=0}^{\infty} \frac{(-1)^p (x^2 + y^2)^p \theta^{(2p+2)}(s)}{4^p p! (p+2)!}, \quad (20)$$

$$B_y(x, y, s) = B_0 \theta(s) + B_0 \sum_{p=0}^{\infty} \frac{(-1)^{p+1} (x^2 + y^2)^p \theta^{(2p+2)}(s)}{4^{p+1} (p+1)! (p+2)!} [x^2 + (2p+3)y^2], \quad (21)$$

$$B_s(x, y, s) = B_0 y \sum_{n=1}^{\infty} \frac{(-1)^n (x^2 + y^2)^n \theta^{(2n+1)}(s)}{4^n n! (n+1)!}. \quad (22)$$

3. Symplectic tracking in SAD

➤ Fringe fields: Hard edge fringe for BEND

- Maxwellian solution for hard-edge dipole field

- * G. Lee-Whiting et al. => E. Forest et al.

- * S. Caspi et al. => M. Bassetti et al. => Y. Cai et al.

$$f = -V_1 = -\frac{1}{2\rho(1+\delta)}p_x y^2$$

Implemented in SAD:

$$x_2 = x_1 - \frac{1}{\rho(1+\delta)}y_1^2,$$

$$p_{y2} = p_{y1} + \frac{1}{\rho(1+\delta)}y_1 p_{x1},$$

$$z_2 = z_1 + \frac{y_1^2}{2\rho(1+\delta)^2}p_{x2}.$$

Apply for LHC and FCCs?:

$$f = \frac{1}{8\rho(1+\delta)}(-p_x x^2 + 2p_y xy - 3p_x y^2)$$

$$x_2 = x_1 - \frac{1}{8\rho(1+\delta)}(x_1^2 + 3y_1^2),$$

$$y_2 = y_1 + \frac{1}{4\rho(1+\delta)}x_1 y_1,$$

$$p_{x2} = \frac{1}{d} \left[p_{x1} - \frac{1}{4\rho(1+\delta)}(y_1 p_{y1} - x_1 p_{x1}) \right],$$

$$p_{y2} = \frac{1}{d} \left[p_{y1} - \frac{1}{4\rho(1+\delta)}(x_1 p_{y1} - 3y_1 p_{x1}) \right],$$

$$z_2 = z_1 + \frac{x_1^2 + 3y_1^2}{8\rho(1+\delta)^2}p_{x2} - \frac{x_1 y_1}{4\rho(1+\delta)^2}p_{y2},$$

$$d = 1 + \frac{3y_1^2 - x_1^2}{16\rho^2(1+\delta)^2}.$$

3. Symplectic tracking in SAD

➤ Solenoid region

- The most complicated part in SAD
- SAD uses GEO and BOUND to define a solenoid region
- Acceptable elements inside solenoid region: DRIFT, BEND(ANGLE=0), QUAD and MULT
- To simplify the transformation: In a SOL region, the coordinate is shifted on the axis of the solenoid, no matter how the design orbit bends there.

3. Symplectic tracking in SAD

➤ Solenoid region

- DRIFT with $BZ \neq 0$ (see p.14 of this talk)
- BEND with $BZ \neq 0$: $L \neq 0$, $K0 \neq 0$, $SK0 \neq 0$, $ANGLE=0$ [Solvable]
- QUAD with $BZ \neq 0$: $L \neq 0$, $K1 \neq 0$, $SK1 \neq 0$ [Approximation needed]
- The general case: MULT with $BZ \neq 0$ [Need multi-step integration]
 - * Step 1: Solenoid fringe at the entrance
 - * Step 2: Rotation of coordinate to cancel $SK1$
 - * Step 3: Calculate the number slices for tracking
 - * Step 4: Nonlinear Maxwellian fringe map at the entrance
 - * Step 5: Linear soft edge fringe at the entrance
 - * Step 6: Body part using “drift-kick-drift” integration
 - * Step 7-11: Maps at exit

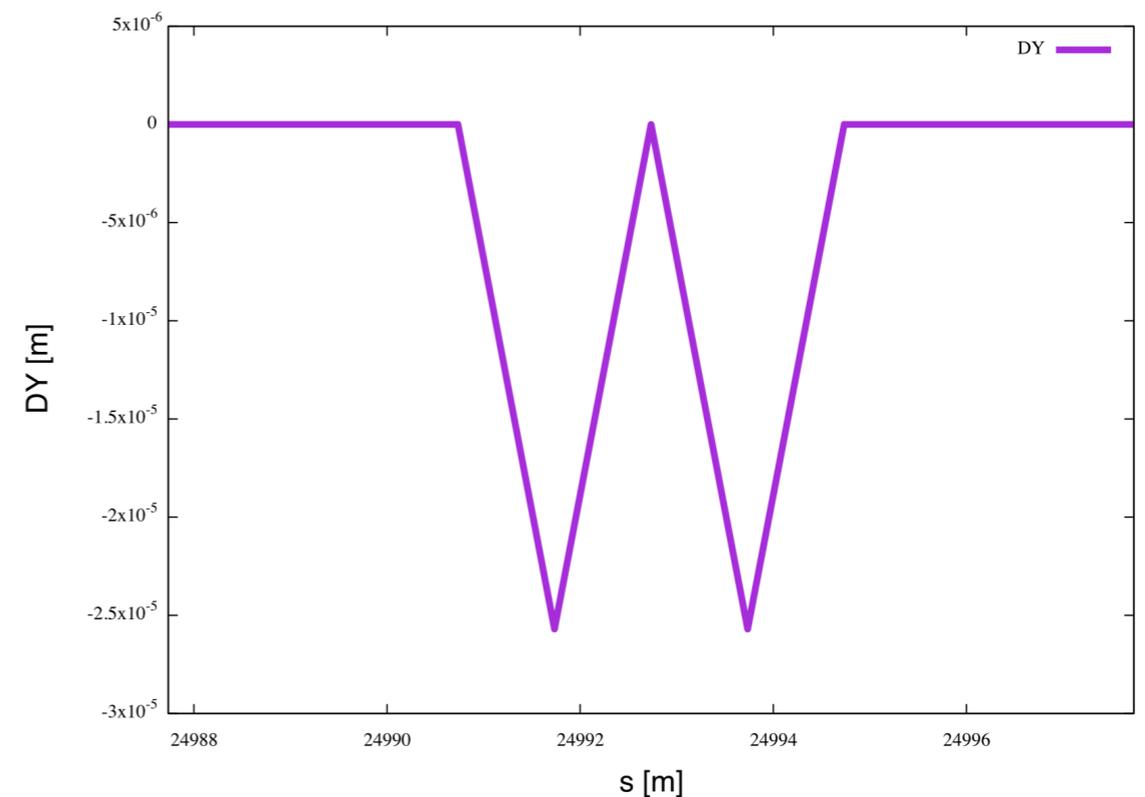
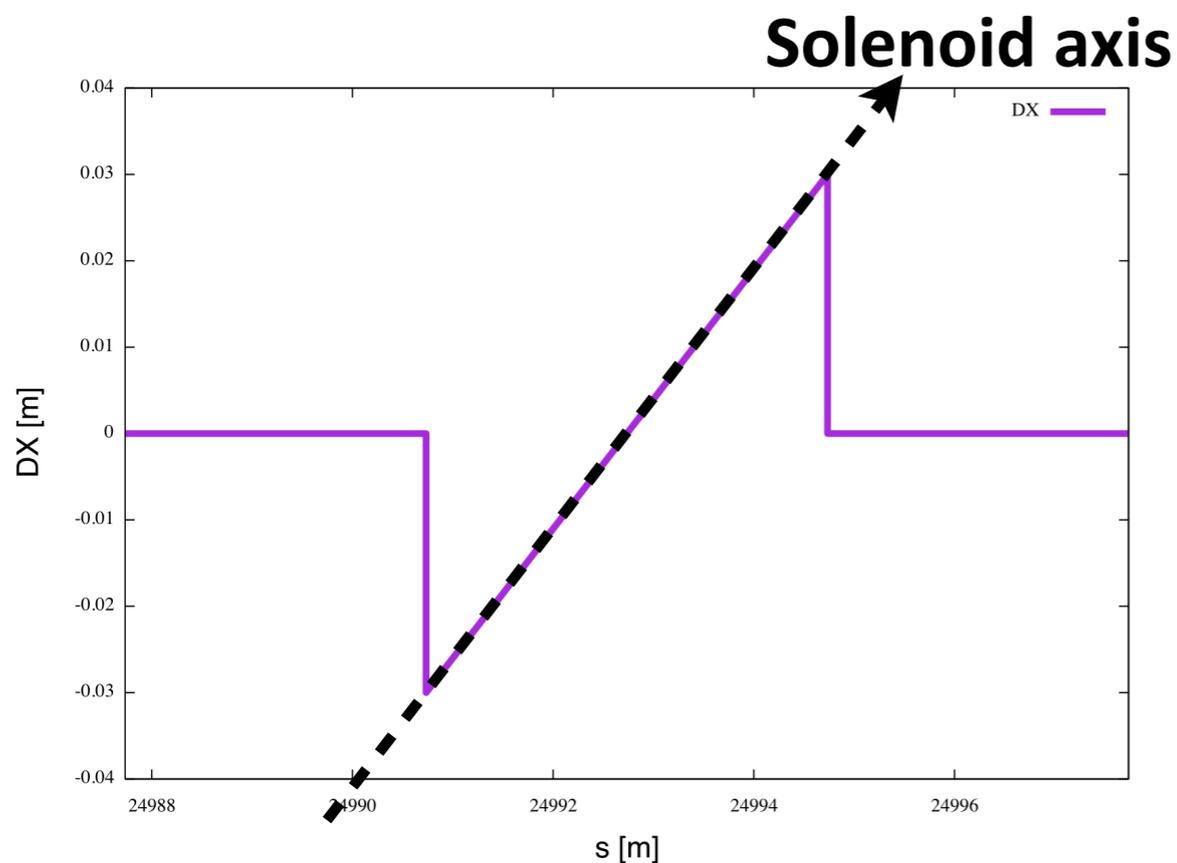
3. Symplectic tracking in SAD

► Tilted solenoid: FCC-ee as an example

• SAD: Orbit patching

```
SOL ES3L =(BZ =0 DX =-.03000219149072553 DY =3.394659937371677e-14 DZ =.0002250210956802542 BOUND =1
      CHI1 =.01499991193234515 CHI2 =-1.69694146889447e-14 CHI3 =-2.545603126440053e-16 F1 =.3 )
ES2L =(BZ =2 F1 =.1 )
ES1L =(BZ =-2 DPX =-.015 BOUND =1 CHI1 =-.015 GEO =1 )
ES1R =(BZ =2 DPX =-.015 BOUND =1 CHI1 =.015 CHI2 =-1.3883951931889808e-28 CHI3 =-2.070759876205156e-30
      GEO =1 )
ES2R =(BZ =-2 F1 =.1 )
ES3R =(BZ =0 DX =.03000219149072553 DY =3.394659937371677e-14 DZ =.0002250210956802542 BOUND =1
      CHI1 =-.01499991193234515 CHI2 =-1.6971323927087947e-14 CHI3 =1.4946246979225722e-21 F1 =.3 )
```

• Beam line: (-ES3L -LX2 -ES2L -LX1 -ES1L -IP IP ES1R LX1 ES2R LX2 ES3R)



3. Symplectic tracking in SAD

➤ Tilted solenoid: FCC-ee as an example

- MAD-X: Solenoid with MATRIX (From A. Morita) [To be tested]

```
...
QC1L1.5 : multipole, at = 24990.459073899623, knl = {0,-.031867324375570986};
ES3L.ent.SOL : matrix, at = 24990.734130022873,
  kick1 = -.03000219149072553, kick2 = .014999349448580609,
  kick3 = 3.394659937371677e-14, kick4 = -1.6971323927087812e-14,
  kick5 = .00022502109568025425, rm11 = 1.0001125092265815,
  rm12 = -9.732766623261589e-19, rm13 = 1.4947928570351675e-21,
  rm14 = -1.4546833374669517e-39, rm16 = 3.376351878790925e-36,
  rm22 = .9998875034303206, rm24 = 2.545675569082e-16, rm26 = .014999349448644554,
  rm31 = -2.5459619810714046e-16, rm32 = 2.477646621241374e-34,
  rm34 = -9.731671720402981e-19, rm36 = -4.700123911412765e-37,
  rm42 = -1.4946246979542352e-21, rm46 = -1.6971323927160166e-14,
  rm51 = -.015001037013850247, rm52 = 1.4598516768440487e-20,
  rm53 = 1.6971323904739247e-14, rm54 = -1.651640530254614e-32;
LX1.1 : solenoid, at = 24992.234130022873, l = 1, ks = .00342619952;
ES1L.ext.SOL : matrix, at = 24992.734130022873,
  kick1 = -1.3494655139198647e-20, kick2 = -.01500112510125922,
  kick3 = 4.337866175973971e-37, rm11 = .9998875021093592,
  rm12 = 8.996774134697688e-19, rm14 = -6.507287317830649e-39,
  rm16 = -1.3494655139252233e-20, rm22 = 1.0001125105478401,
  rm24 = -7.23372550967171e-21, rm26 = -.015001125101323174,
  rm31 = 7.232911730810398e-21, rm32 = -3.0099993164431145e-54,
  rm34 = 8.995762016584963e-19, rm36 = 4.337866175992464e-37,
  rm51 = .014999437506392037, rm52 = -6.242063821814771e-36,
  rm54 = 4.337866175992464e-37;
IP.1 : marker, at = 24992.734130022873;
IP.2 : marker, at = 24992.734130022873;
ES1R.ent.SOL : matrix, at = 24992.734130022873, kick2 = .01499943750632809, kick3 = -4.337
LX1.2 : solenoid, at = 24993.234130022873, l = 1, ks = .00342619952;
LX2.2 : solenoid, at = 24994.234130022873, l = 1, ks = -.00342619952;
ES3R.ext.SOL : matrix, at = 24994.734130022873, kick1 = -.02999881634709996, kick2 = -.015
QC1R1.1 : multipole, at = 24995.009186146122, knl = {0,-.03306130971283883};
...
```

3. Symplectic tracking in SAD

➤ Tilted solenoid: FCC-ee as an example

- MAD-X: Solenoid with misalignments (From E. Gianfelice-Wendt)
- Beam line: (ES2L ES1L IP ES1R ES2R)
- Orbit patching also used (?)

```
!Definitions
bsol=2;! fixed at all energies
ks_es1r:= bsol/brho;!+
ks_es2r:=-bsol/brho;!-
ks_es1l:= bsol/brho;!+
ks_es2l:=-bsol/brho;!-
value, bsol, brho, ks_es1r;
ES1R: SOLENOID, L=1 , KS:=ks_es1r;
ES2R: SOLENOID, L=1 , KS:=ks_es2r;
ES1L: SOLENOID, L=1 , KS:=ks_es1l;
ES2L: SOLENOID, L=1 , KS:=ks_es2l;
```

```
!Misalignments
SELECT, FLAG=ERROR,clear;
SELECT, FLAG=ERROR, PATTERN=ES1R;
EALIGN, DX =-0.0, DY =0,DS =0,
        DPHI=-.0, DTHETA=-0.015, DPSI=0;
EPRINT;
SELECT, FLAG=ERROR,clear;
SELECT, FLAG=ERROR, PATTERN=ES2R;
EALIGN, DX =-.015, DY =0,DS =0,
        DPHI=-.0, DTHETA=-0.015, DPSI=0;
EPRINT;
SELECT, FLAG=ERROR,clear;
SELECT, FLAG=ERROR, PATTERN=ES1L;
EALIGN, DX =.015, DY =0,DS =0,
        DPHI=-.0, DTHETA=-0.015, DPSI=0;
EPRINT;
SELECT, FLAG=ERROR,clear;
SELECT, FLAG=ERROR, PATTERN=ES2L;
EALIGN, DX =.030, DY =0,DS =0,
        DPHI=-.0, DTHETA=-0.015, DPSI=0;
EPRINT;
set, format="14.12f";
SELECT, FLAG = ERROR, CLASS=solenoid;
esave,FILE ="sol_data.dat";
ESAVE;
```

4. Summary

➤ Lattice translation

- Translators collected
- Examples uploaded to MAD-X svn repository
- Benchmark of SAD and MAD-X/PTC
- Tests, benchmarks and contribution to translator developments/improvements are welcomed [Integrate efforts from IHEP]

➤ Symplectic tracking in SAD

- Symplectic transformations as less approximation as possible
- Soft-edge fringe maps are useful for MAD-X
- Simple (tilted) solenoid (such as FCC-ee design) seems to be translatable to MAD-X
 - MULT fields superimposed with solenoid fields (such as SuperKEKB FFS) are the most difficult part in SAD <-> MAD-X translation