Magnet alignment

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Alignment data & tolerances

INOITH are	alignment errors. The units are milli-meters.				
Crab Cavities LER (3.5 GeV) (planning)	·	LER		HER	
HER (8 GeV)	Area	dR	dPhi	dR	dPhí
Surgerine KEKB	Tsukuba	0.08	0.09	(< LER + HER)	
W B-Factory E	North Arc	0.09	0.12	0.10	0.10
	West Arc	0.11	0.14	0.12	0.14
	South Arc	0.09	0.10	0.11	0.10
Transport Lines wight internation	East Arc	0.10	0.17	0.11	0.16
AND SOU ONO	All Arc Sections	0.10	0.14	0.11	0.13
South arc	Nikko	0.01	0.27	0.03	0.11
	Fuji	0.01	0.27	0.03	0.19
e+ target (8 GeV) e- gun	Oĥo	0.04	0.08	0.03	0.14
J-Arc	All Straight Sect.	0.02	0.22	0.03	0.15
R: perpendicular to the beau	am				
φ: along the beam	Tolerance	0.15	0.50	0.15	0.50
At the	e completion of c	construc	tion	KEK	Prenrint 99-14

Table 2: Summary of the standard deviations of the alignment errors. The units are milli-meters.

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KEK Preprint 99-131 November 1999 A

Tunnel level survey along the beamline

- South has been sinking with respect to the IP
 - A few mm per year.
 - As was reported in "Magnet issues, circumference drift" KEKB Review, 2003

http://www-kekb.kek.jp/MAC/2003/

Beam level markers

- Beam level markers were installed on the tunnel wall every ~30 m in Nov. and Dec., 1995.
 - The centers of the TRISTAN quadrupole magnets were used as reference.

Tunnel Level Changes (R. Sugahara,Y. Ohsawa)

The beam level markers on the tunnel wall have been surveyed times since 1996 (+1 in 2004)

- 1st survey: June&July, 1996
- 2nd survey: August & September, 1997
 - The height of the markers on the tunnel wall were re-adjusted.
- 3rd survey:Feb. 1998
- 4th survey: Oct.1998
- 5th survey: Jul.2001
- 6th survey: Aug.2002



Tunnel Level Changes



Tunnel Level Changes



(2)Largest shift between Fuji and Oho (south tunnel), 2.5mm/year



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Tunnel level survey summary

- The tunnel has become deformed since the initial magnet alignment was completed.
- The south tunnel has been sinking with respect to the IP.

Why is south tunnel sinking? →Well →Heavier

Why is the south tunnel sinking?



*The south tunnel section is more heavily built up.

As it goes through cycles of expansion and contraction, it loses its grip on the surrounding sub-soil?

*3 wells

The ground retains a large amount of water, which is pumped up at the rate of several hundred tons/day.

Magnet level

- The tunnel shape has been changing.
- The south arc section keeps sinking with respect to the IP.
- It is natural to expect the levels of the magnets have drifted since 1998.
 - We do not measure the magnet level as often as the markers since it is time/cost consuming, but there are data taken in 2004.

Magnet level along the beamline



Magnet level drift similar to the tunnel is seen as expected.
→smooth level change is probably OK.
Some local ups and downs exist here and there.

 \rightarrow This might be a problem.

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Magnet level at Fuji straight section



Not too smooth...

Better adjust the level for KEKB upgrade, at least.

Lattice Errors Y.Ohnishi's slide

Multipole components and fringe field have been included in the design lattice.

Following errors are produced with random numbers according to Gaussian. The values are one standard deviation(σ).

	alignment error ∆x (µm)	alignment error ∆y (µm)	rotation error Δθ (mrad)	gradient error ∆k/k
Bending magnet	100	100	0.1	1x10-4
Quadrupole magnet	100	100	0.2	3x10-4
Sextupole magnet	100	100	0.2	5x10 ⁻⁴

 \rightarrow These were satisfied originally but things have moved around since.

Magnet level survey summary

- The center height (level) of the magnets has changed since the completion of construction. It follows the tunnel level in general.
- There are some local level changes seen, which might degrade the machine performance if not smoothed out, at least locally.

Vibration measurements in the KEKB tunnel

- Depends on where in the tunnel →will be presented at some other occasion.
- Introduce *some data* presented at IWAA 2004 (International Workshop on Accelerator Alignment 2004 @ CERN)

Vibration measurements

Tsukuba experimental hall



Specifications of the acceleration sensors

Acceleration sensors MG-102S (Tokkyo-kiki Corp.)			
Maximum Input	+/- 2 G		
Sensitivity	$0.5102 \text{ V s}^2/\text{m}$		
Frequency range	DC-400 Hz		
Cross talk	1/1000		
Weight	160 g		
Amplifier/OSP-06 (Tokkyo-kiki Corp.)			
Frequency range	0.1-400 Hz		
Data logger/DS-2000 (Ono Sokki Corp.)			
A/D conversion	24 bit		
Axis definition			

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2	x	Horizontal plane, perpendicular to beam direction
2	y	Horizontal plane, parallel to beam direction
,	v	Vertical







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VIBRATION MEASUREMENTS IN THE KEKB TUNNEL

Mika Masuzawa, Yasunobu Ohsawa, Ryuhei Sugahara and Hiroshi Yamaoka

- 1. Motions of the QA2RP/QB4RP magnet (non-IR magnets) were measured along with the floor motion near by.
- A clear vibration peak at ~13 Hz was observed.
- When normalized to the floor motion the vertical peak disappeared.
- Horizontal peaks were fitted to obtain damping factors and natural (resonant) freq. of the system.
- The damping factor of the magnet system was found to be ~2%. This agrees with the typical damping factor of bolt (rivet) structures.
- The integrated amplitude is ~0.4 µm for freq.>1 Hz.
- 2. Motions of the IR magnets were measured. The floor motion near the IP was also measured.
- The IR magnet PSD curves have more complicated structures than those of the non-IR magnets.
- The vibration amplitude is largest in the x direction in all IR magnets, ~0.35µm for QCS.
- The IR magnets (and the supporting table) has a peak ~ 8 Hz.
- The vibration amplitude of the IR magnets are much smaller than the size of the colliding beams (~2µm vertically and ~100µm horizontally).

Vertical vibration amplitude is less than 0.1 µm for for freq. >10Hz

Vibration depends on location, time of the day, day of the week and so on (I will skip the details here).



KEK, Tsukuba, Japan

http://www-conf.kek.jp/iwaa08/index.html Visit the site and register NOW!